Dynamic Field Theory: Selection Decisions

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Recall from last lecture …

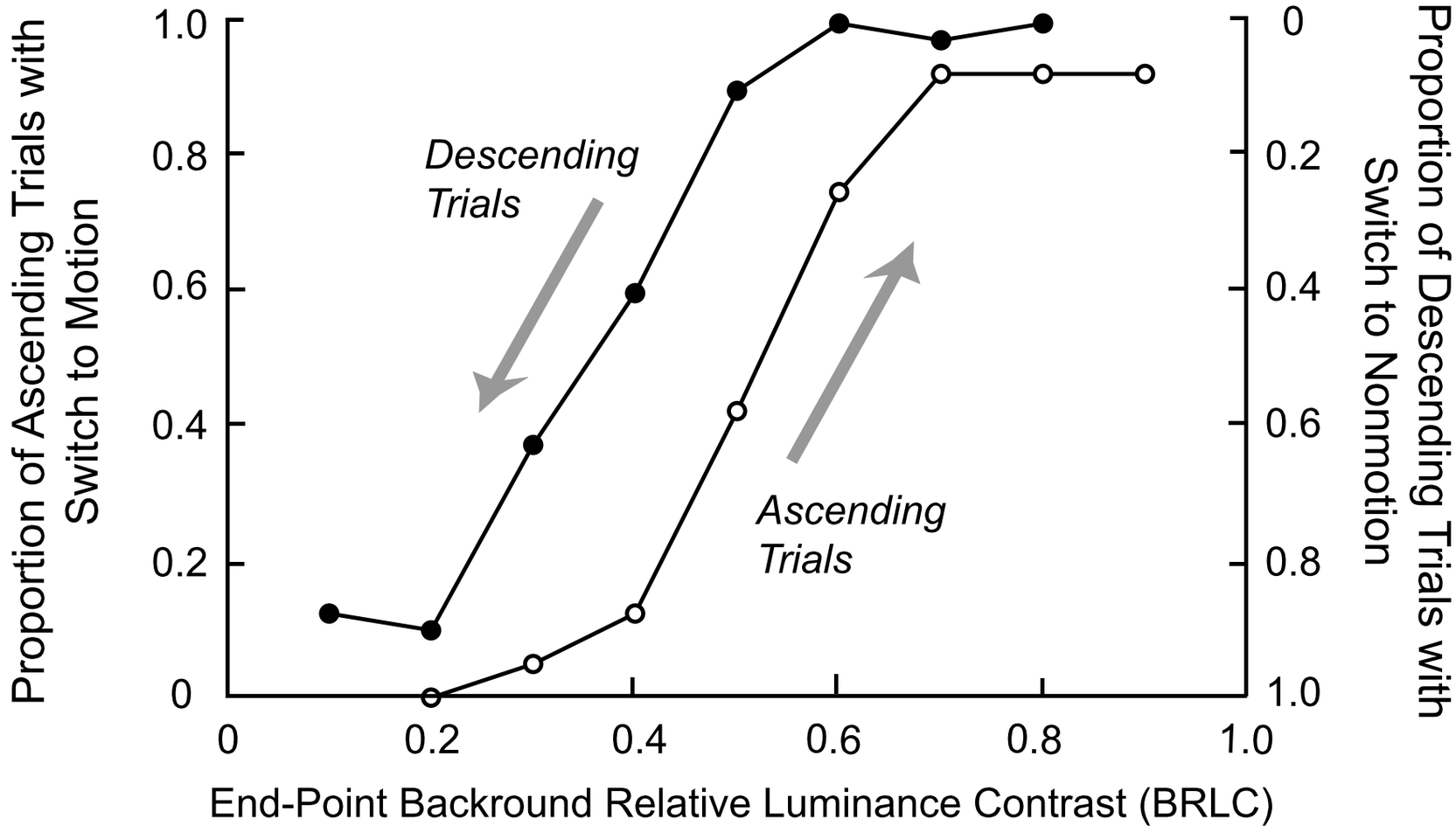
Solutions and instabilities

- input driven solution (sub-threshold) vs. self-stabilized solution (peak, supra-threshold)
- detection instability
- reverse detection instability
- selection
- selection instability
- memory instability
- detection instability from boost

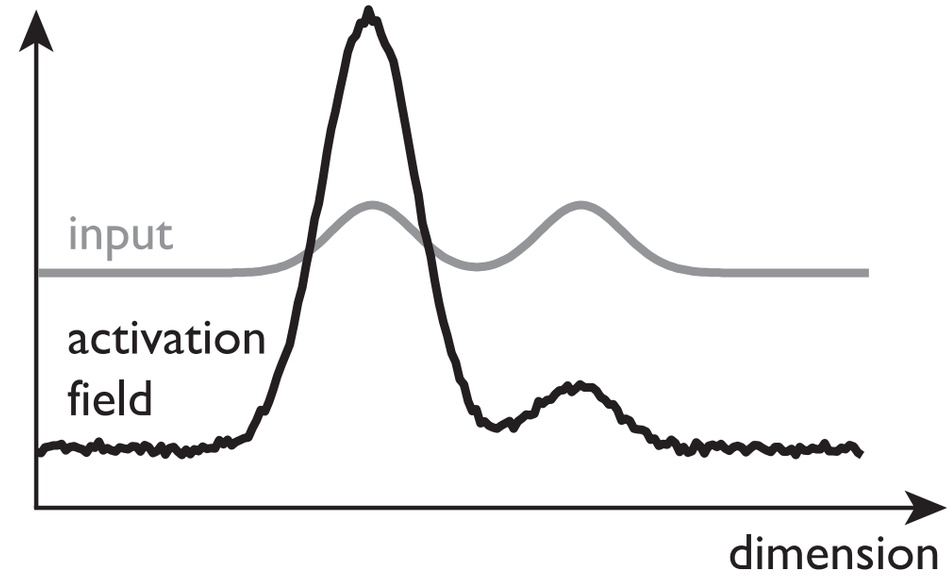
Psychophysical evidence for the detection instability

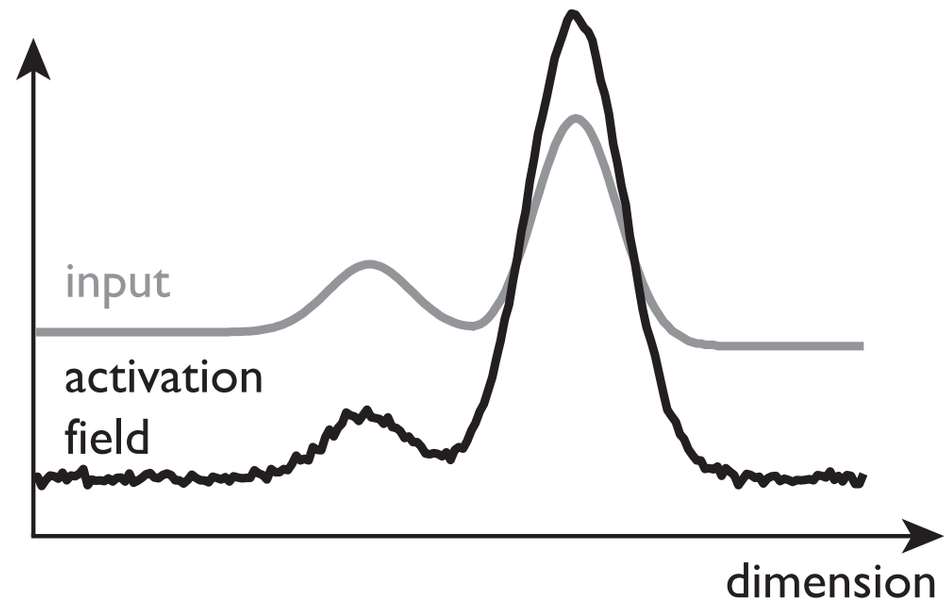
- perceptual hysteresis of motion detection

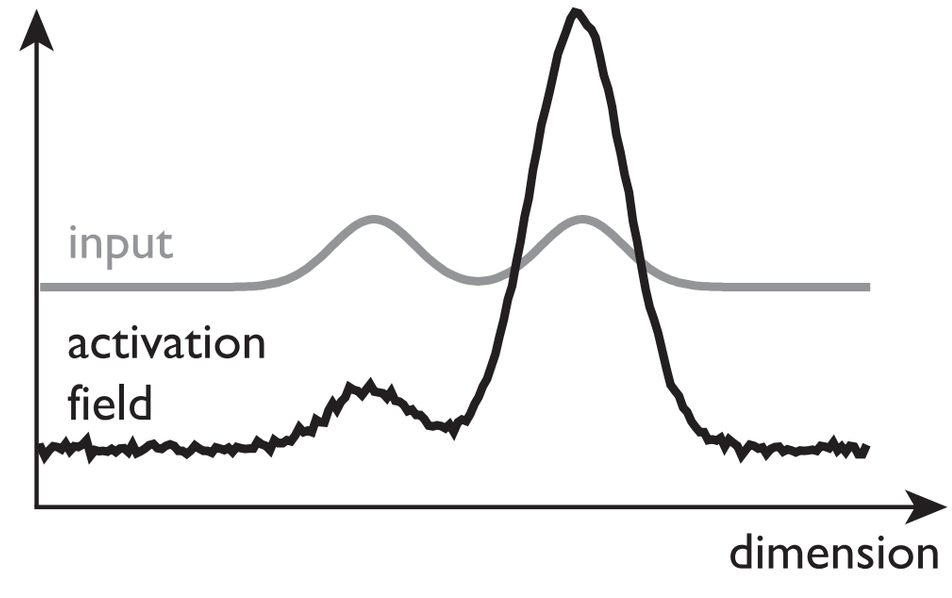
H. S. Hock, G. Schöner / Seeing and Perceiving 23 (2010) 173–195



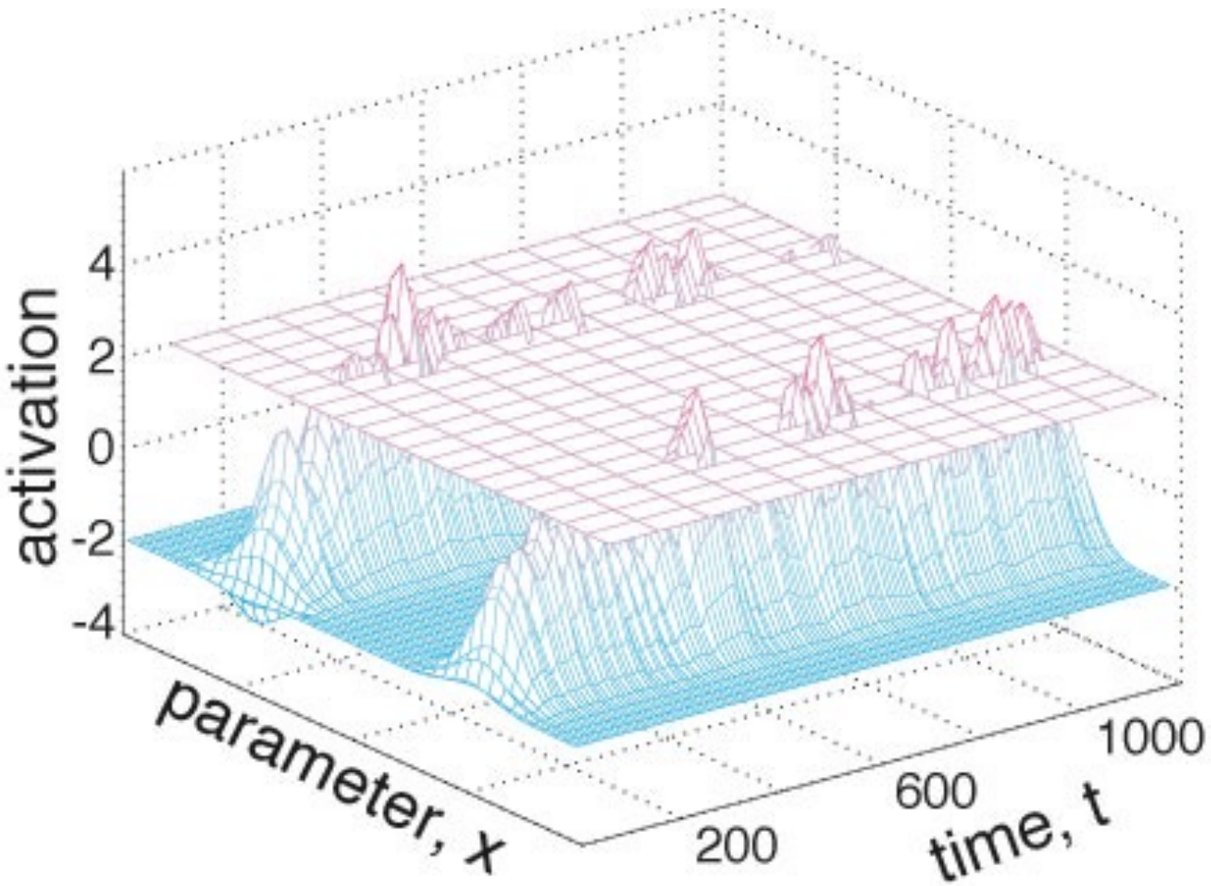
selection instability

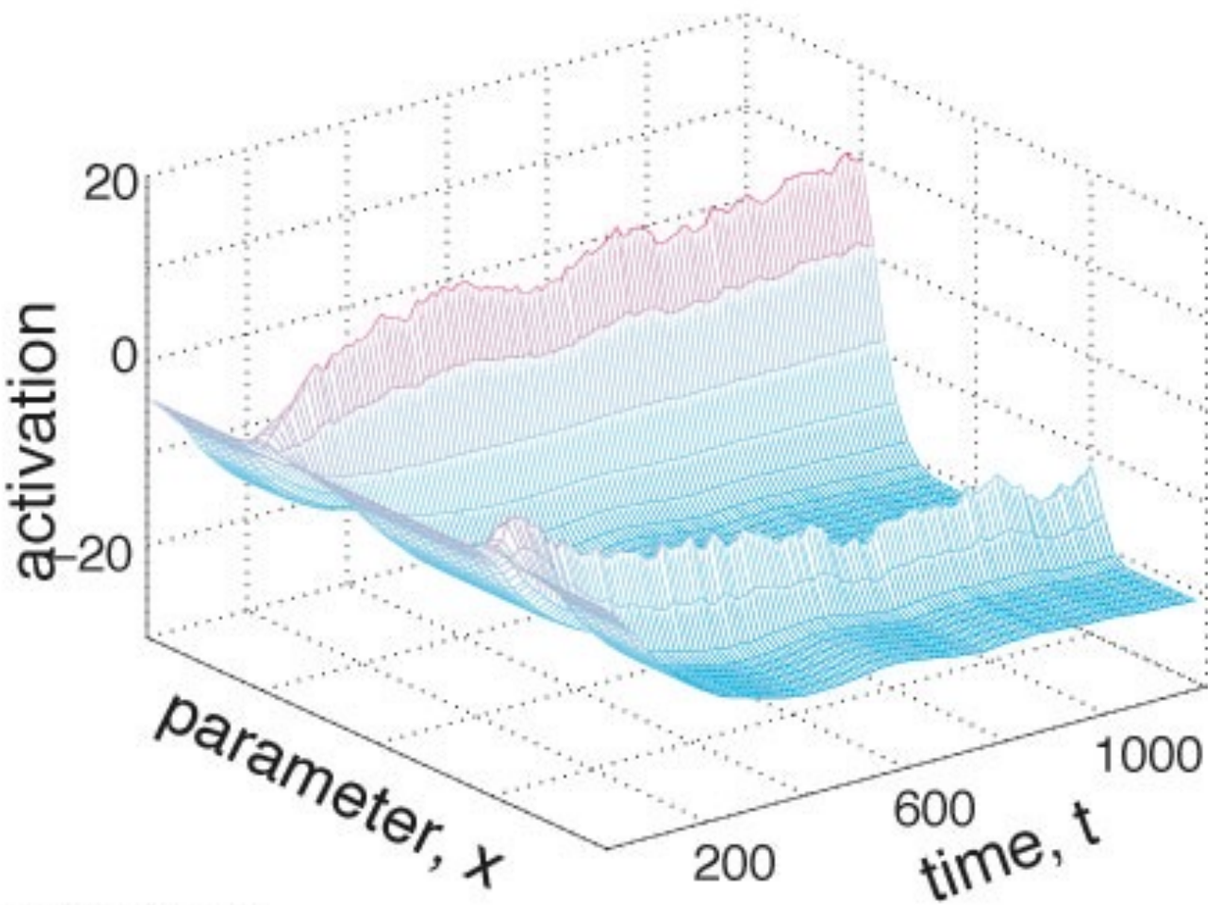






stabilizing selection decisions





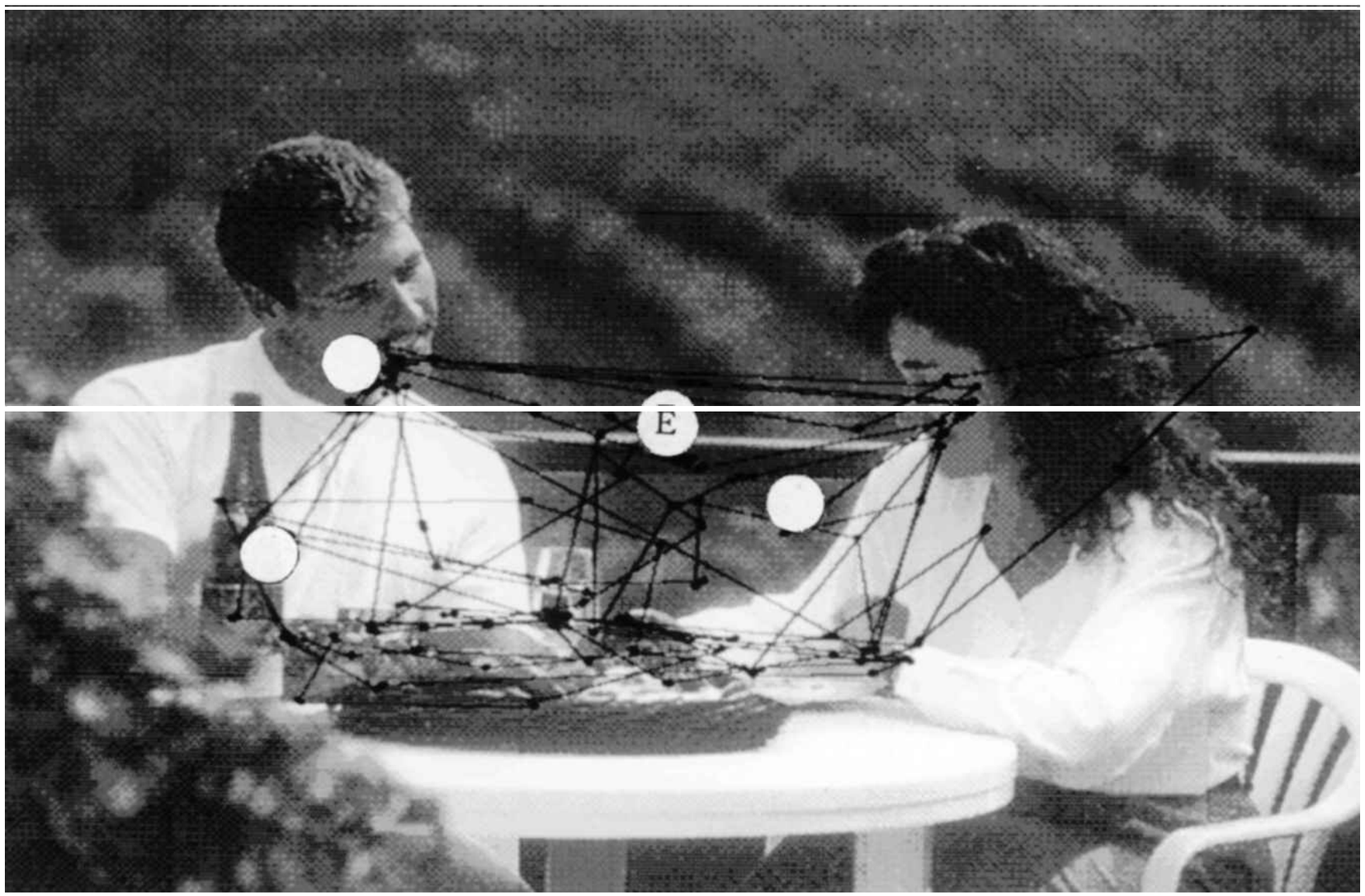
[Wilimzig, Schöner, 2006]

behavioral signatures of selection decisions

- in most experimental situations, the correct selection decision is cued by an "imperative signal" leaving no actual freedom of "choice" to the participant (only the freedom of "error")
- reasons are experimental
- when performance approaches chance level, then close to "free choice"
- because task set plays a major role in such tasks, I will discuss these only a little later

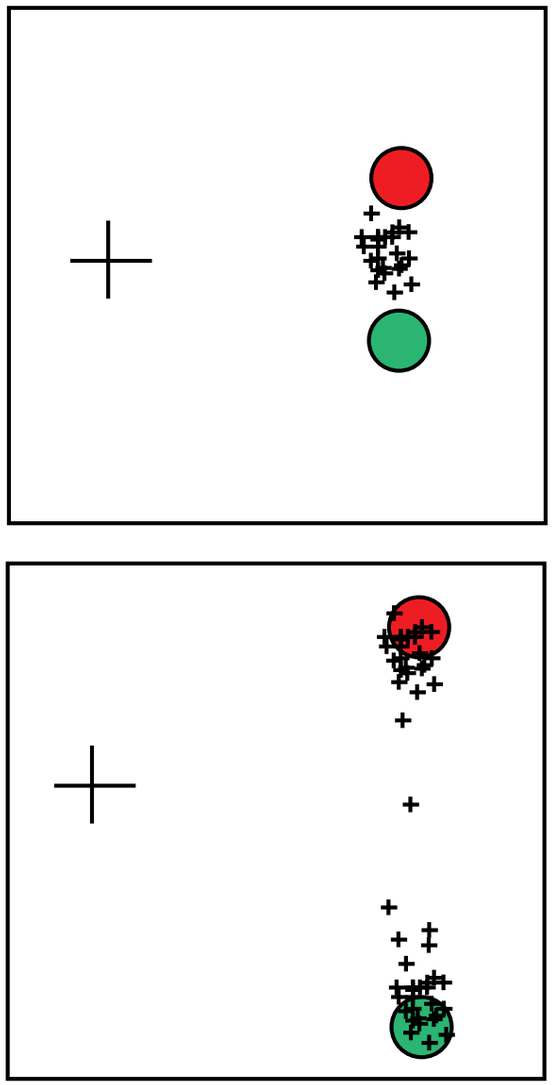
one system of "free choice"

- selecting a new saccadic location

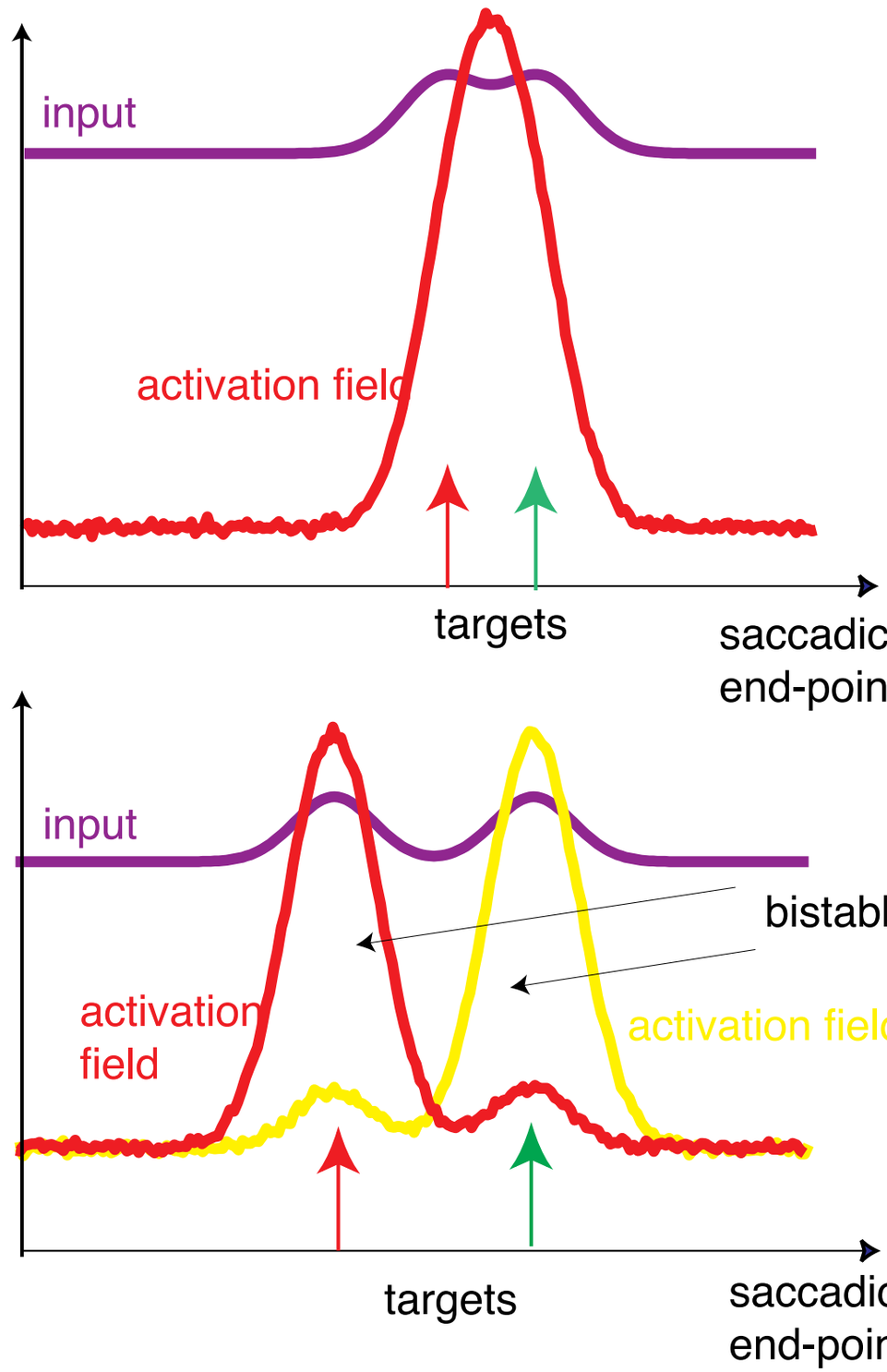


[O'Reagan et al., 2000]

saccade generation



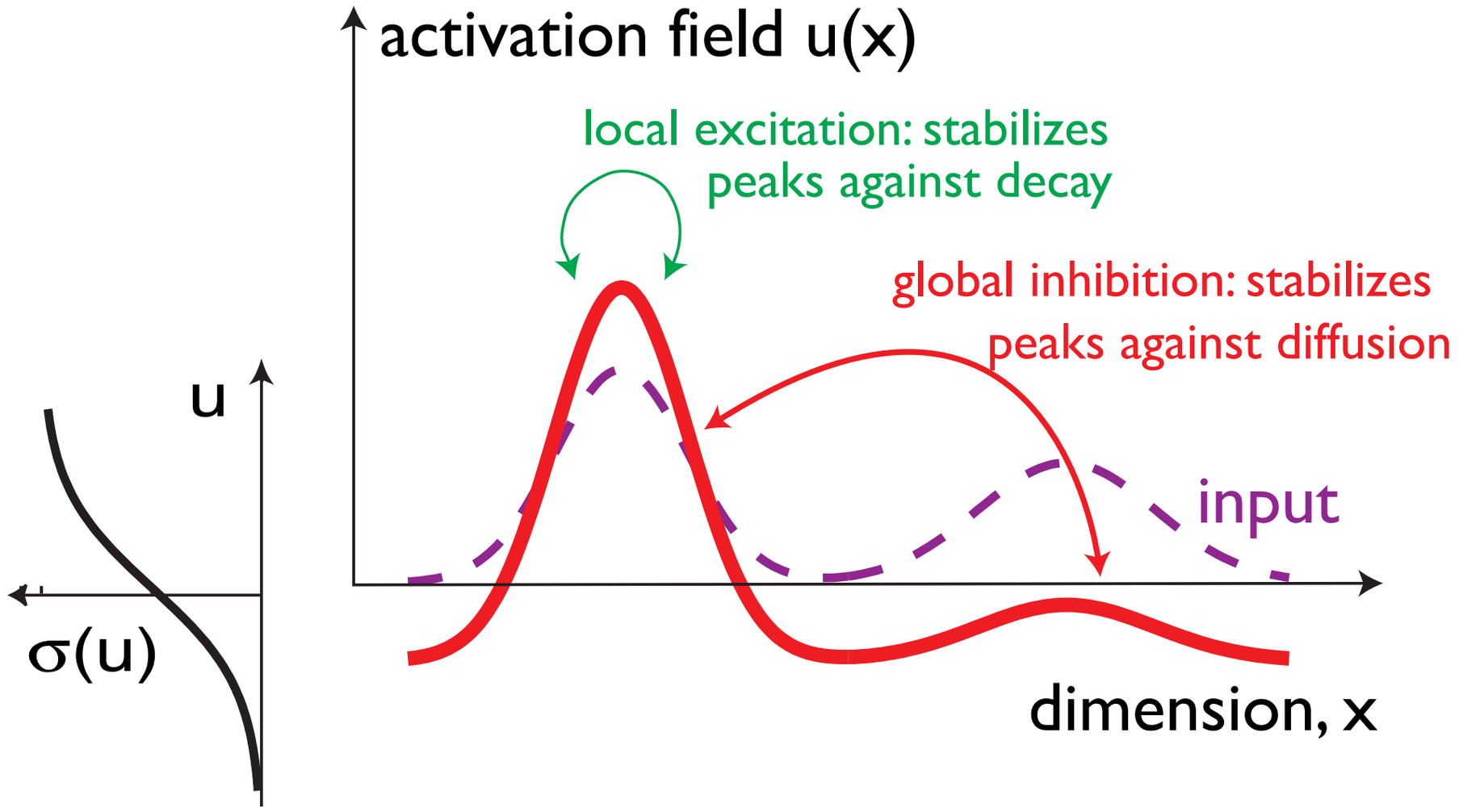
[after: Ottes et al., Vis. Res. 25:825 (85)]



[after Kopecz, Schöner: Biol Cybern 73:49 (95)]

… so far we assumed

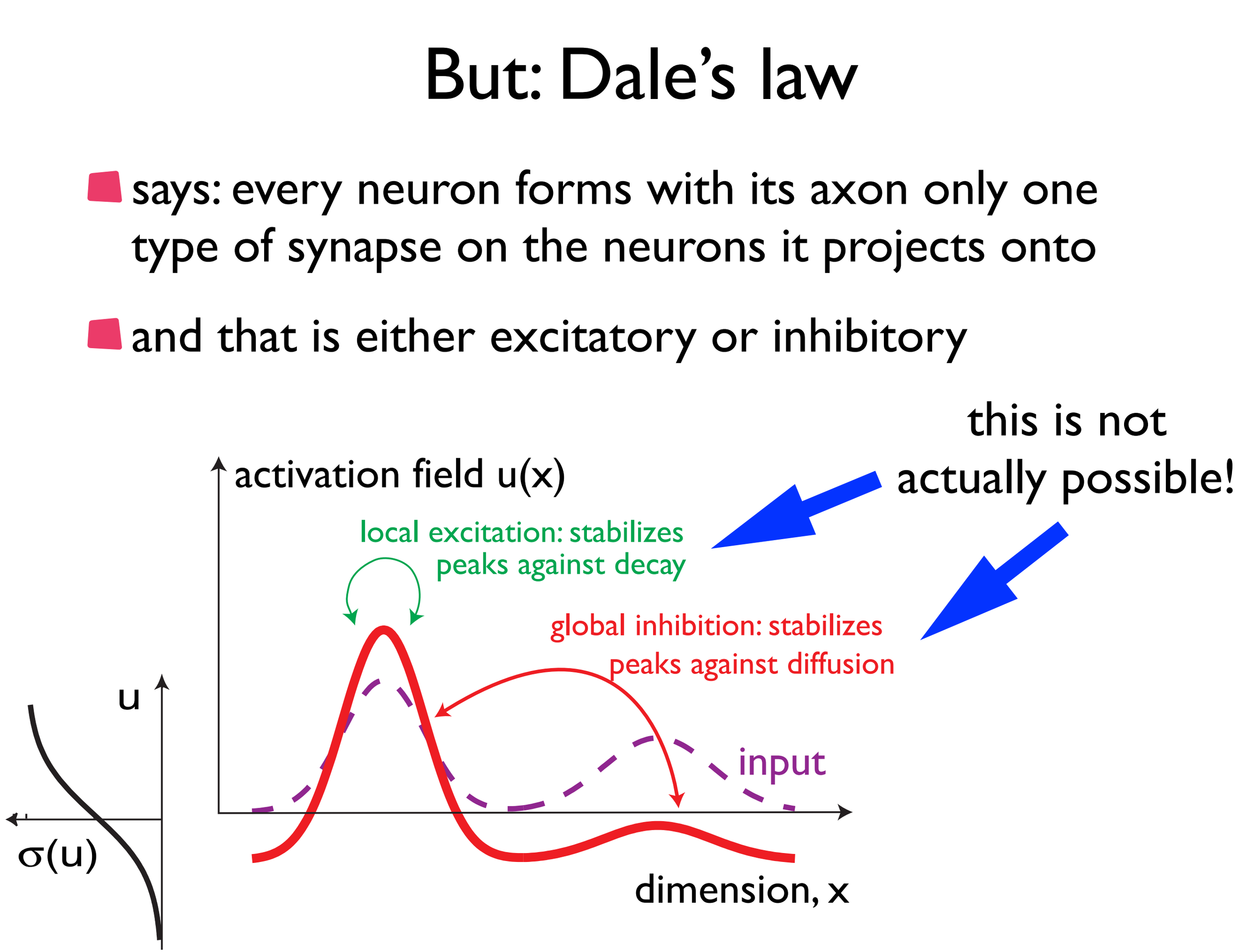
- that a single population of activation variable mediates both the excitatory and the inhibitory coupling required to make peaks attractors



But: Dale's law

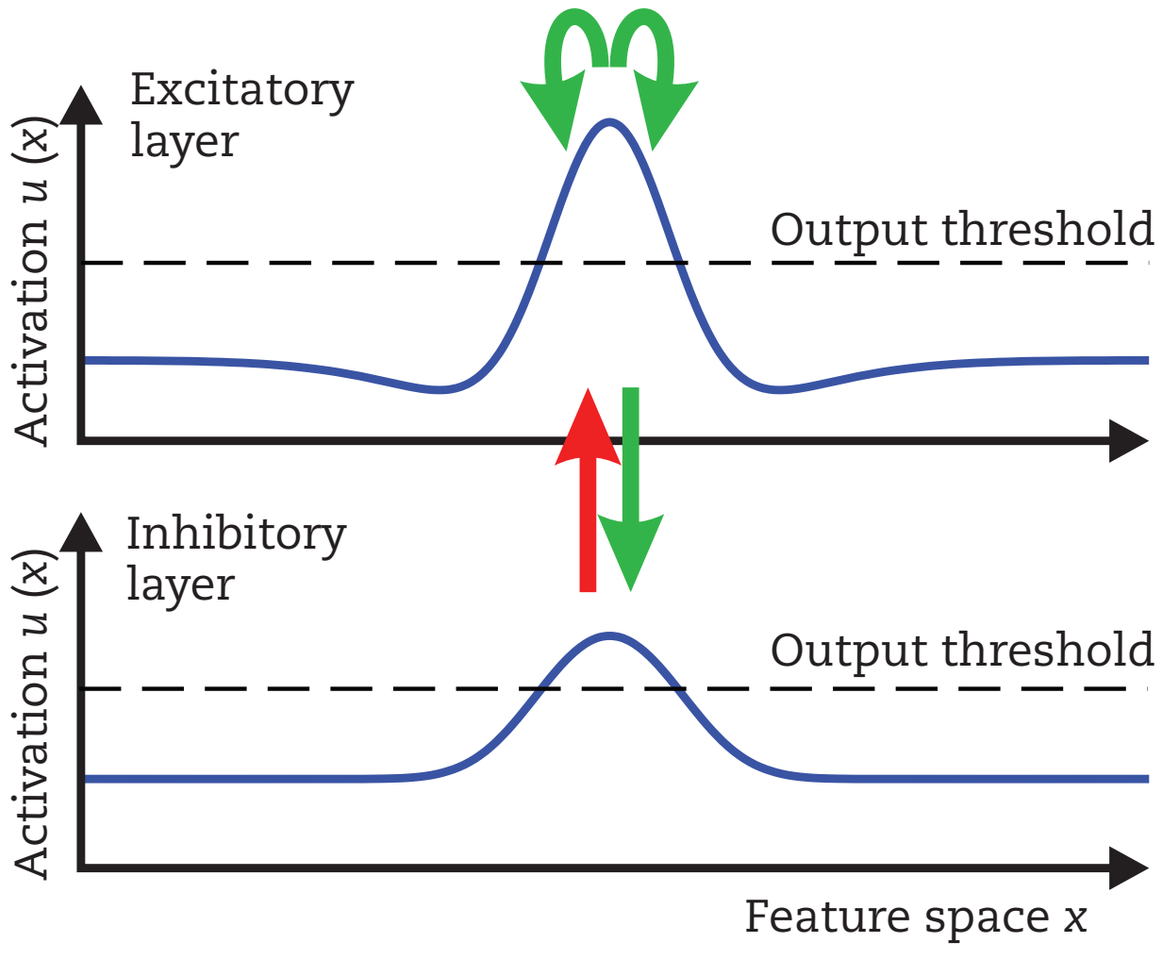
- says: every neuron forms with its axon only one type of synapse on the neurons it projects onto
- and that is either excitatory or inhibitory

this is not actually possible!



2 layer neural fields

- inhibitory coupling is mediated by inhibitory interneurons that
  - are excited by the excitatory layer
  - and in turn inhibit the inhibitory layer



[chapter 3 of the book]

2 layer Amari fields

$$\tau_u \dot{u}(x,t) = -u(x,t) + h_u + s(x,t) + \int k_{uu}(x-x')g\big(u(x',t)\big)dx' - \int k_{uv}(x-x')g\big(v(x',t)\big)dx'$$

$$\tau_v \dot{v}(x,t) = -v(x,t) + h_v + \int k_{vu}(x-x')g\big(u(x',t)\big)dx'$$

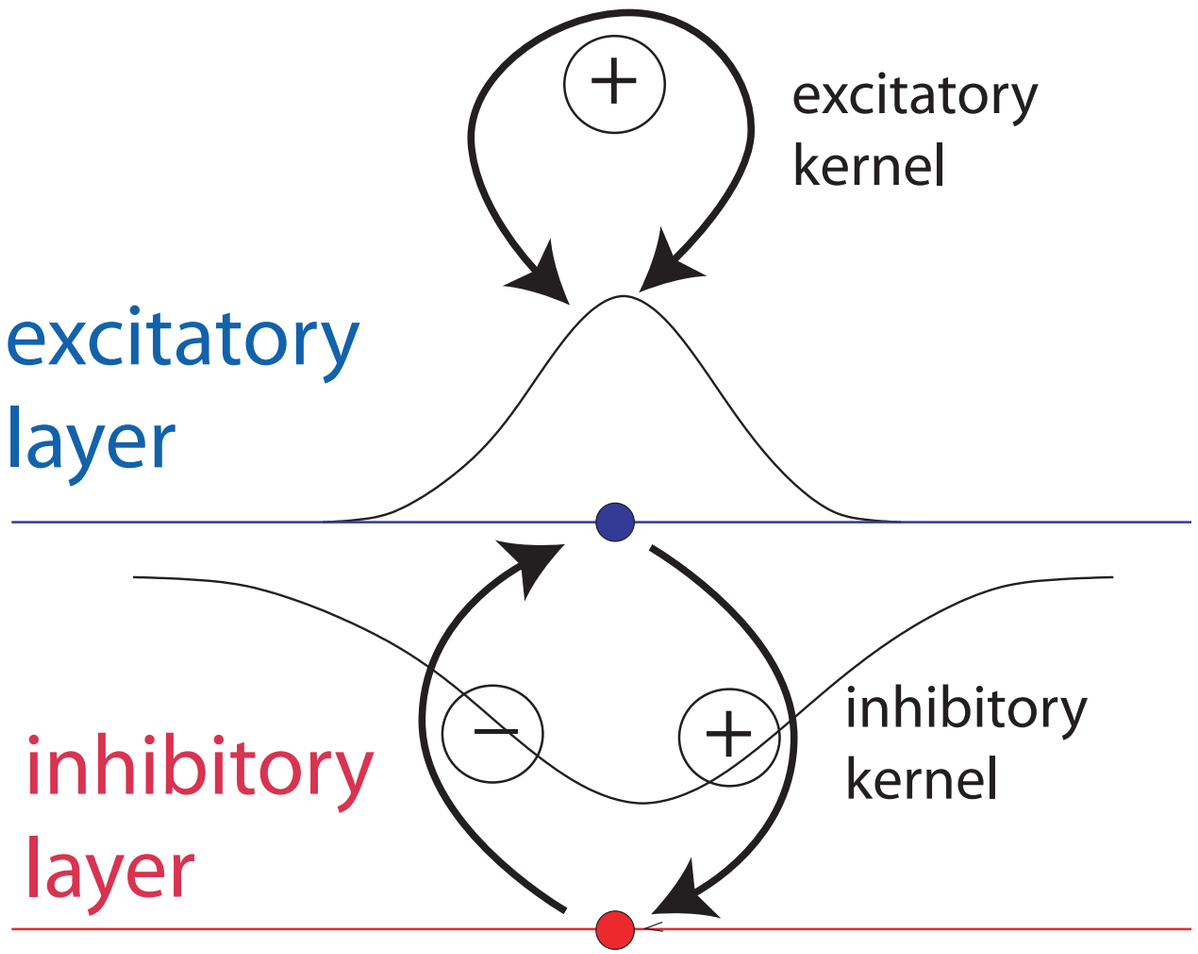
with projection kernels

$$k_{uu}(x-x') = c_{uu} \cdot \exp\left(-\frac{(x-x')^2}{2\sigma_{uu}^2}\right)$$

simulation

Implications

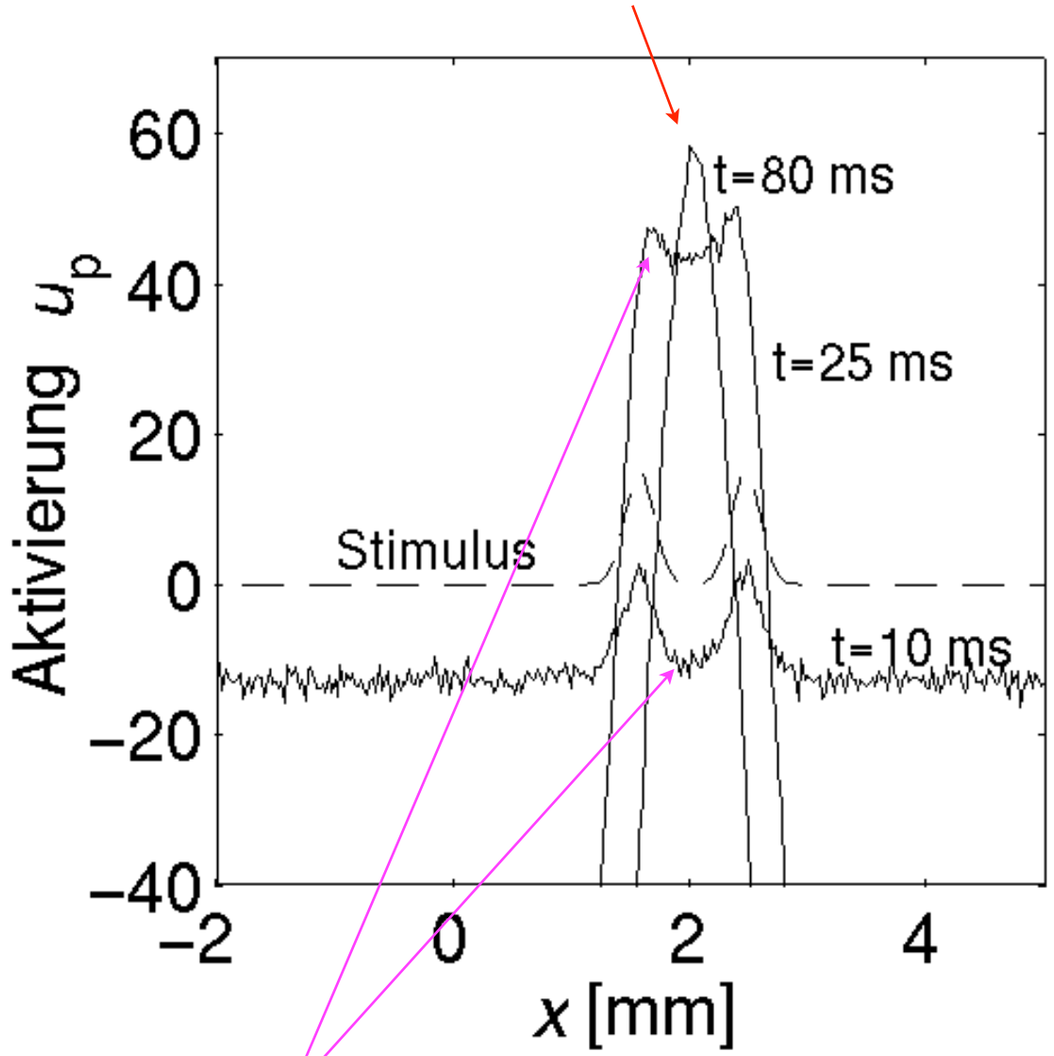
- the fact that inhibition arises only after excitation has been induced has observable consequences in the time course of decision making:
  - initially input-dominated
  - early excitatory interaction
  - late inhibitory interaction



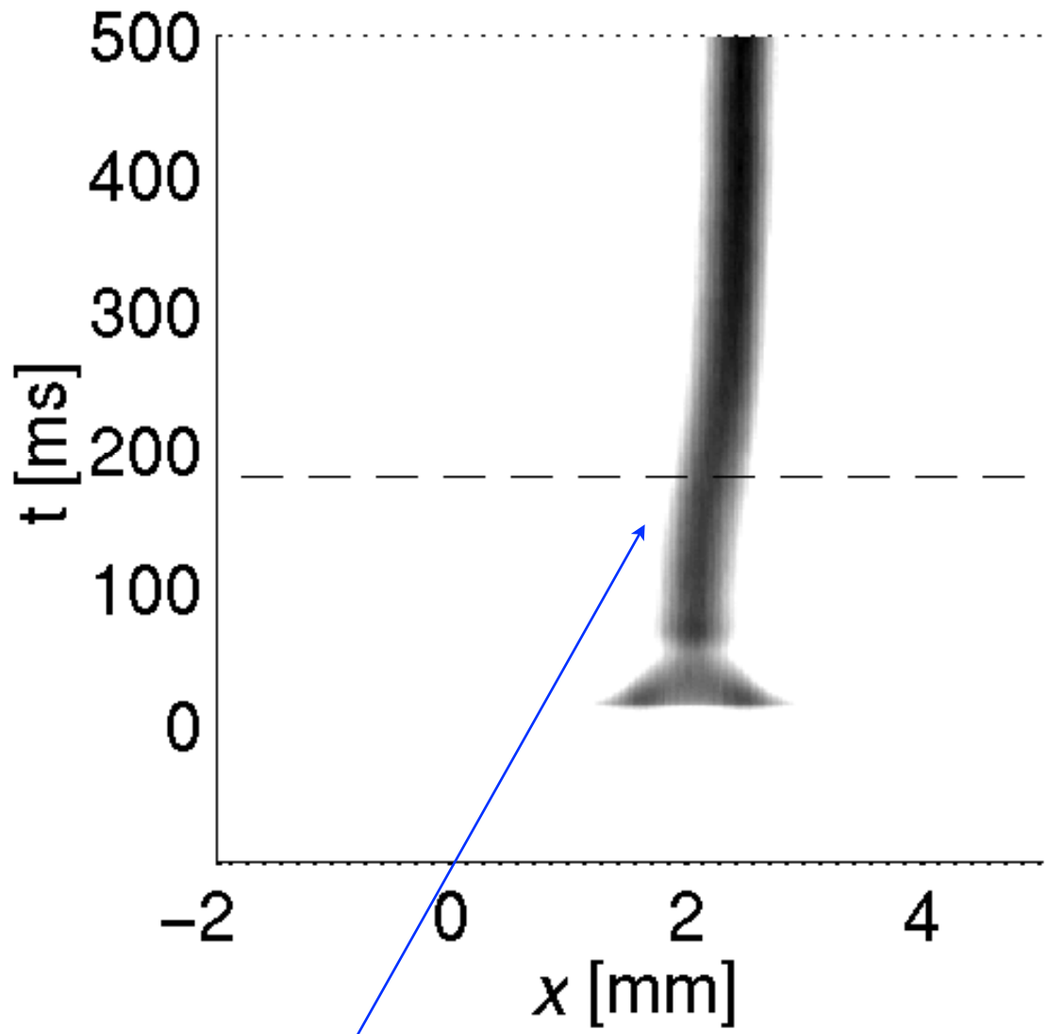
[figure: Wilimzig, Schneider, Schöner, Neural Networks, 2006]

time course of selection

intermediate: dominated by excitatory interaction



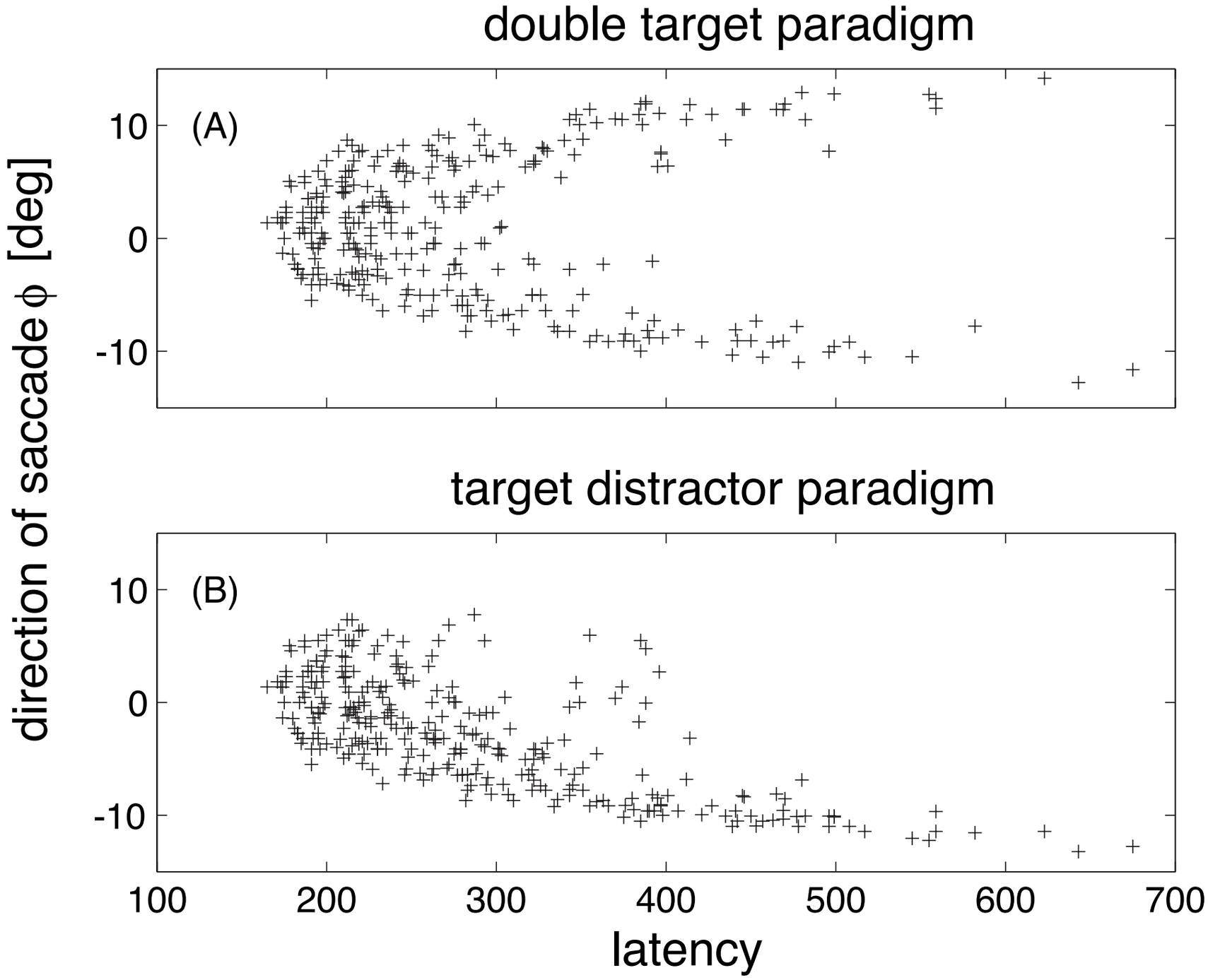
early: input driven



late: inhibitory interaction drives selection

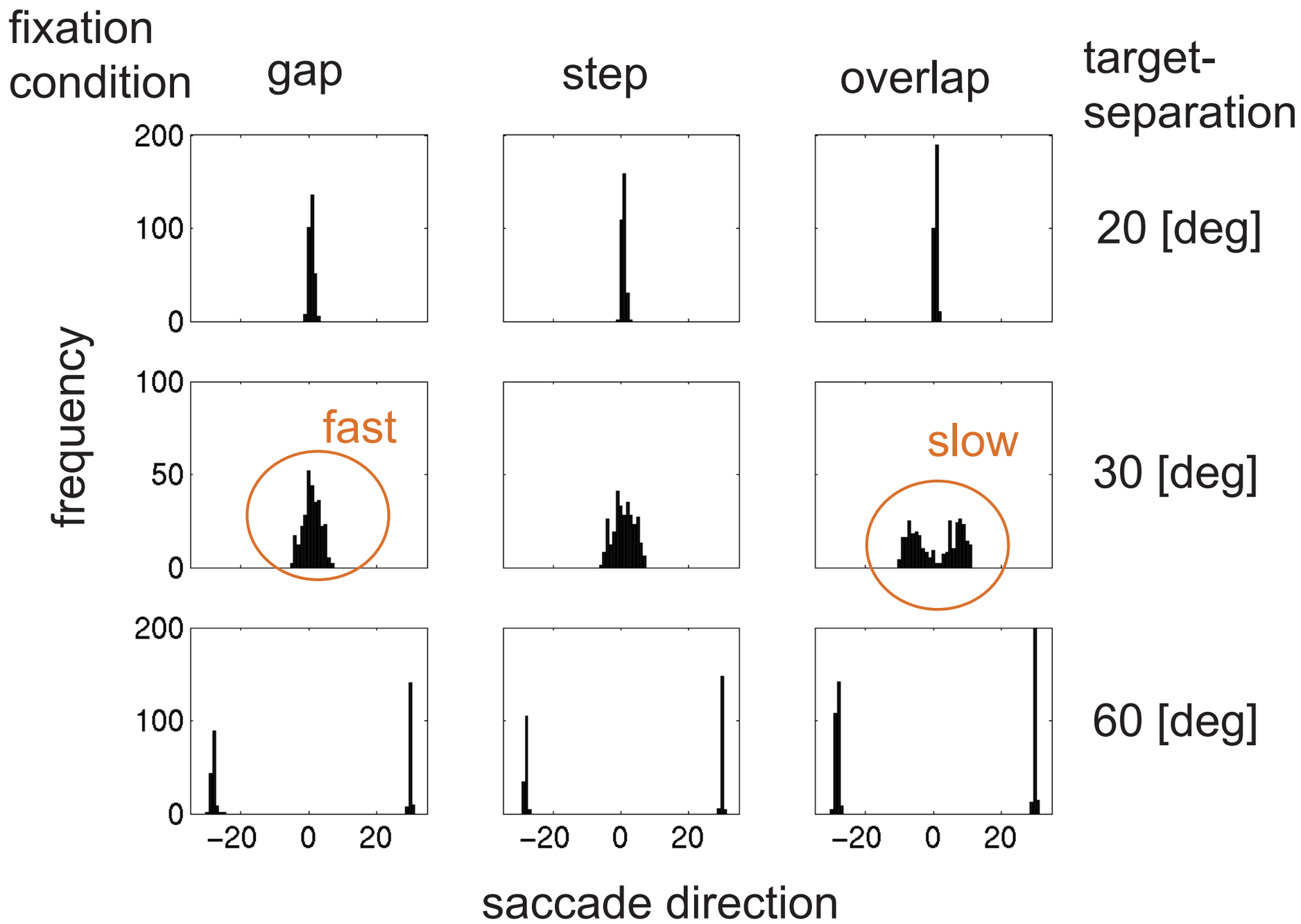
[figure: Wilimzig, Schneider, Schöner, Neural Networks, 2006]

=> early fusion, late selection



[figure: Wilimzig, Schneider, Schöner, Neural Networks, 2006]

fixation and selection



[figure: Wilimzig, Schneider, Schöner, Neural Networks, 2006]

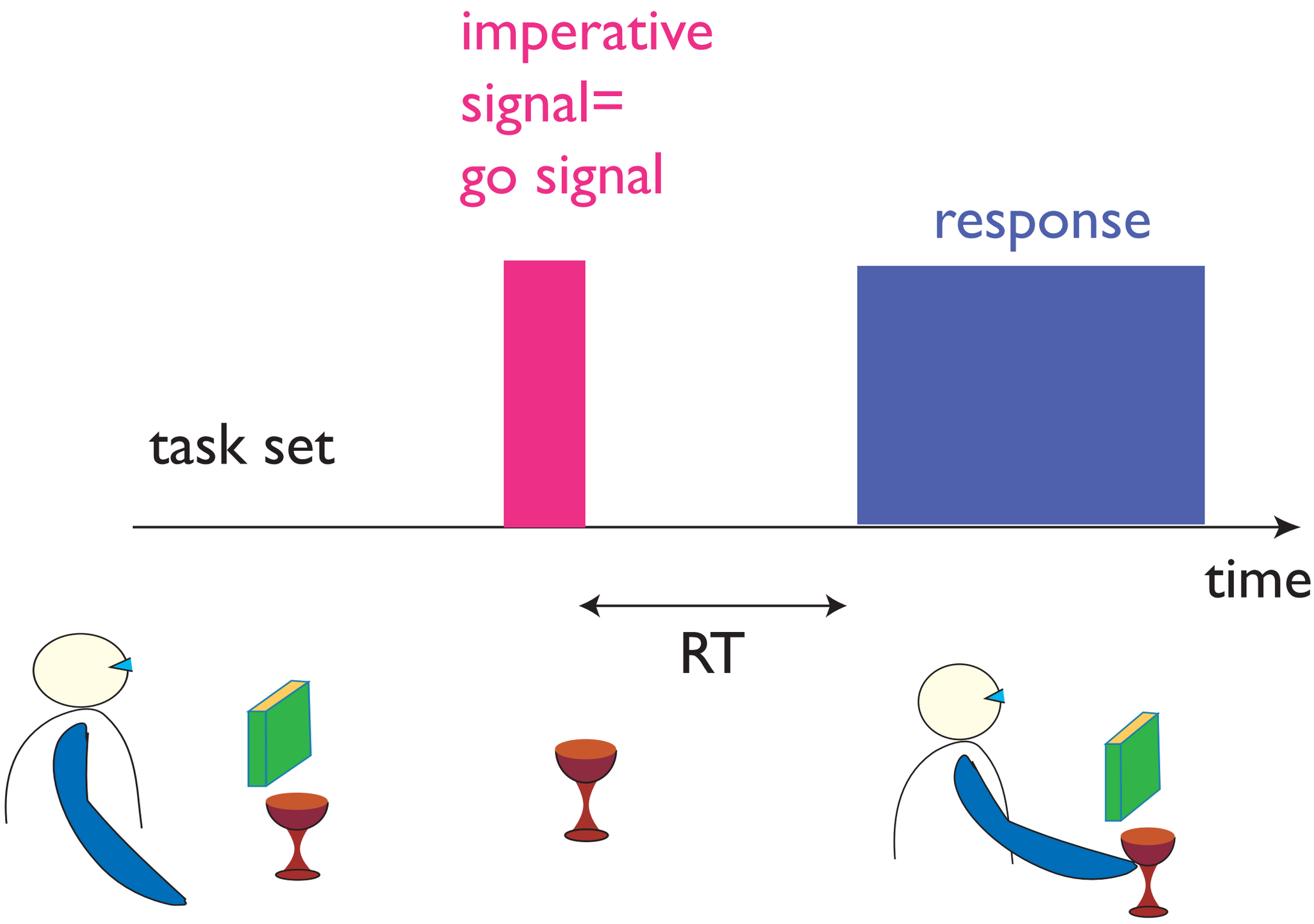
2 layer fields afford oscillations

- => simulation
- (oscillatory states for enhanced coupling among fields)
- (generic nature of oscillations)

studying selection decisions in the laboratory

- using an imperative signal...

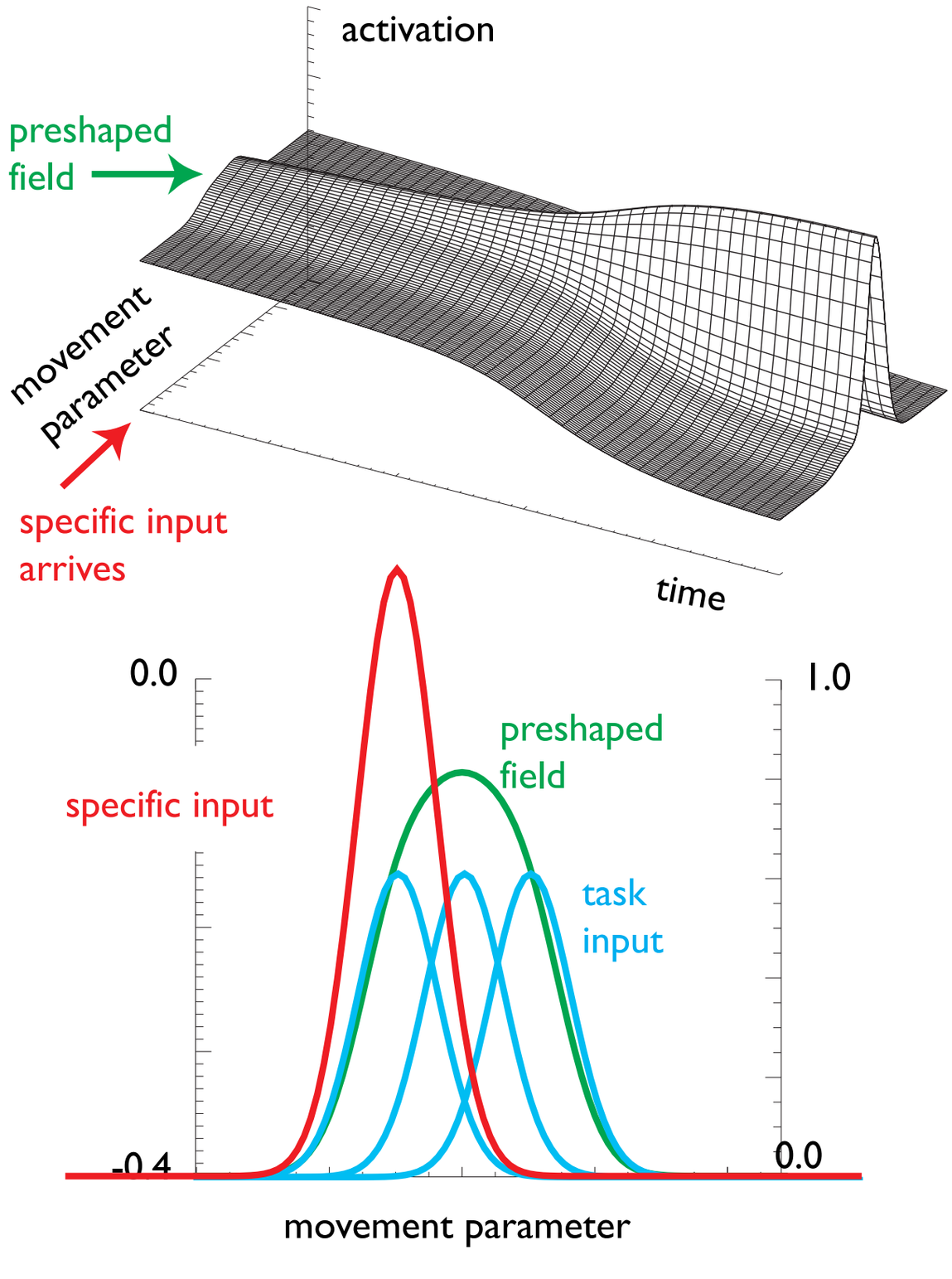
reaction time (RT) paradigm



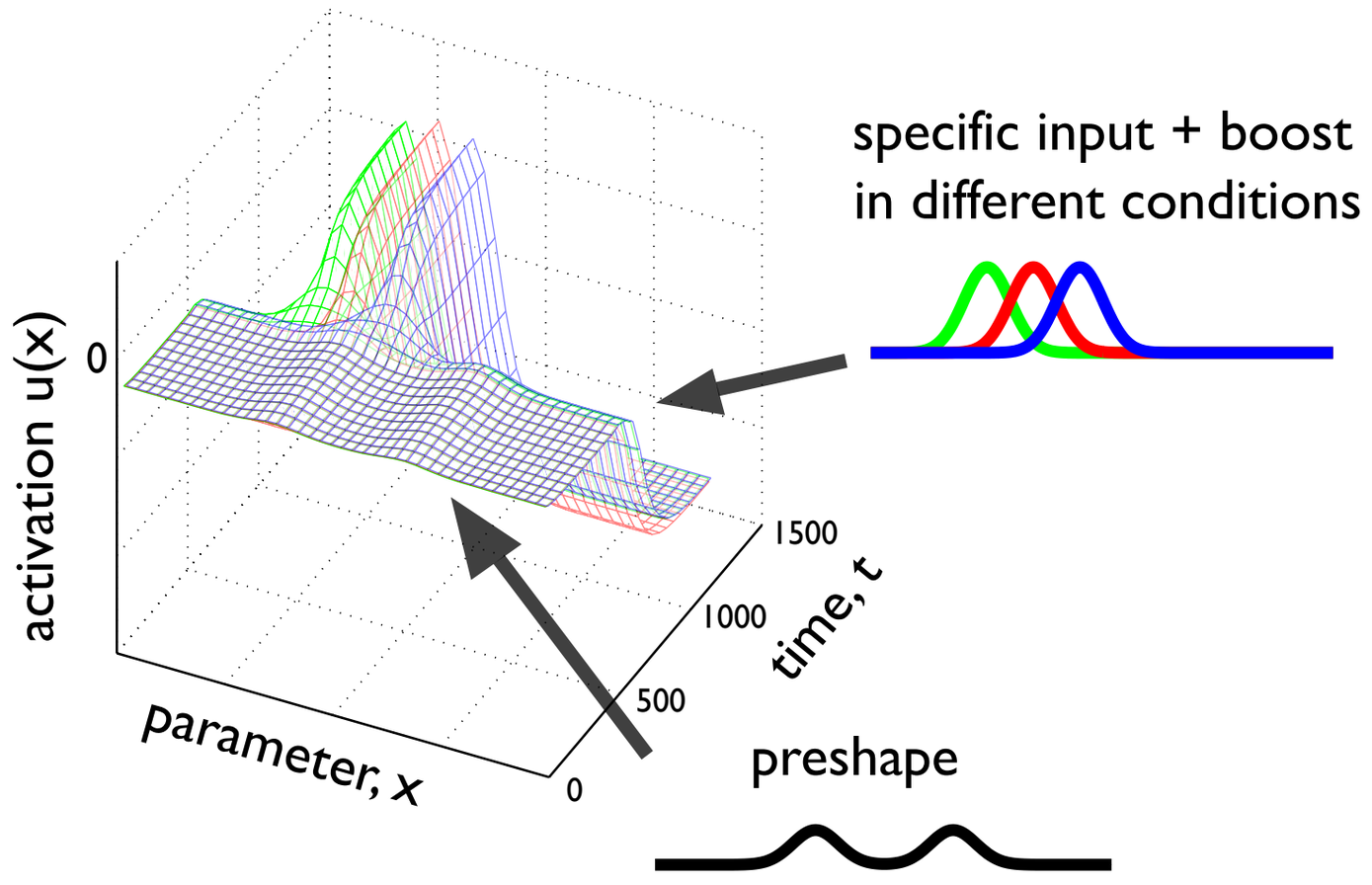
the task set

- is the critical factor in such studies of selection: which perceptual/action alternative/choices are available…
  - e.g., how many choices
  - e.g., how likely is each choice
  - e.g., how "easy" are the choices to recognize/perform
- because the task set is known to the participant prior to the presentation of the imperative signal, one may think of the task set as a "preshaping" of the underlying representation (pre=before the decision)

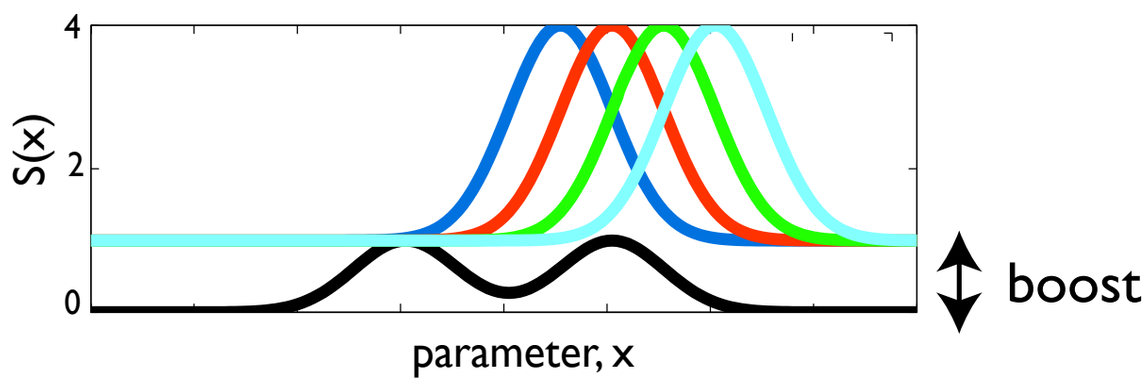
notion of preshape

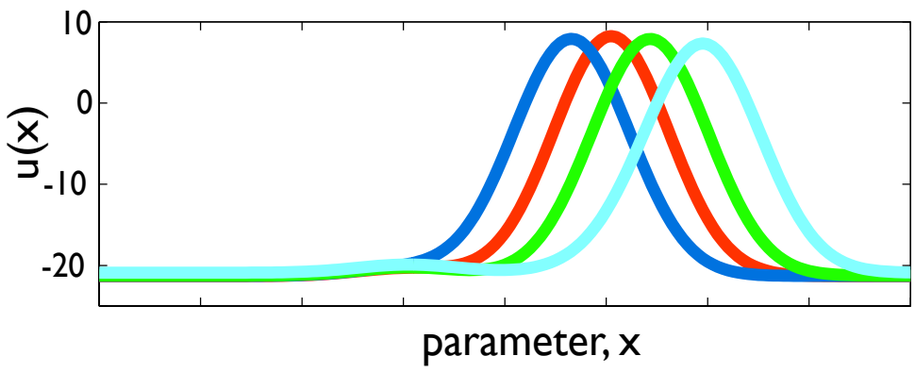


weak preshape in selection



- specific (imperative) input dominates and drives detection instability

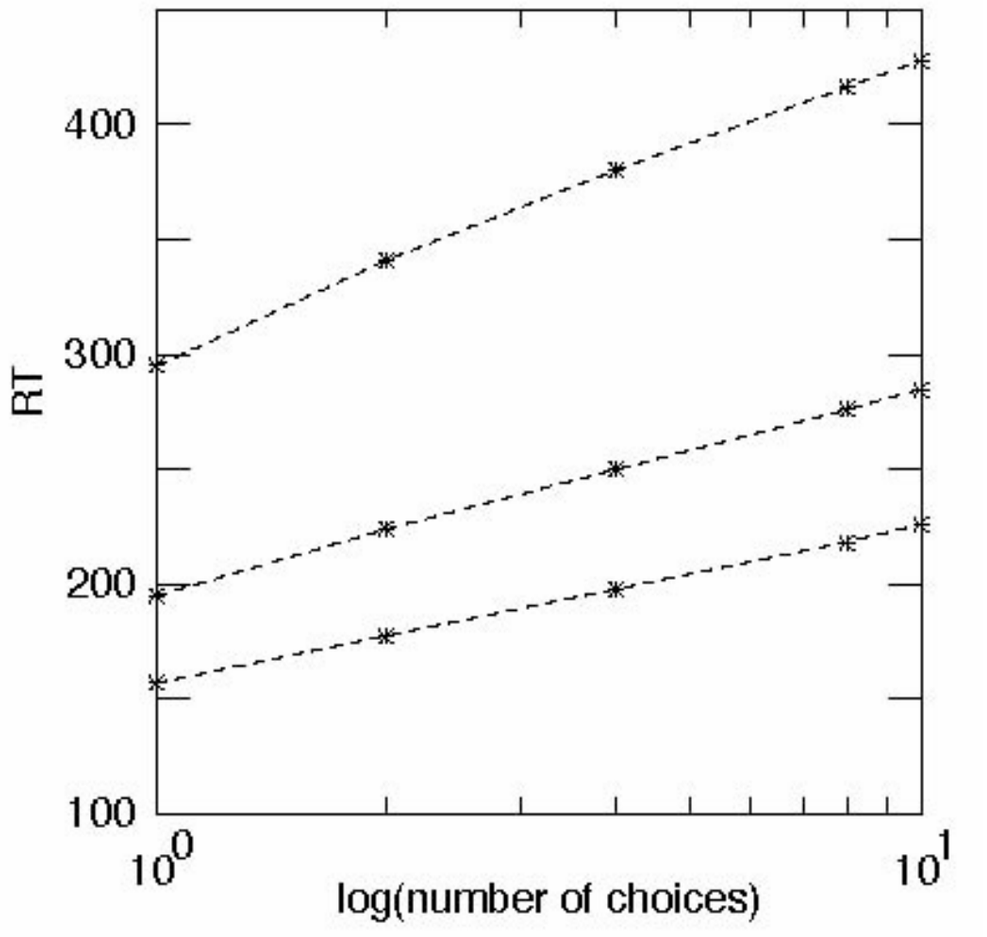


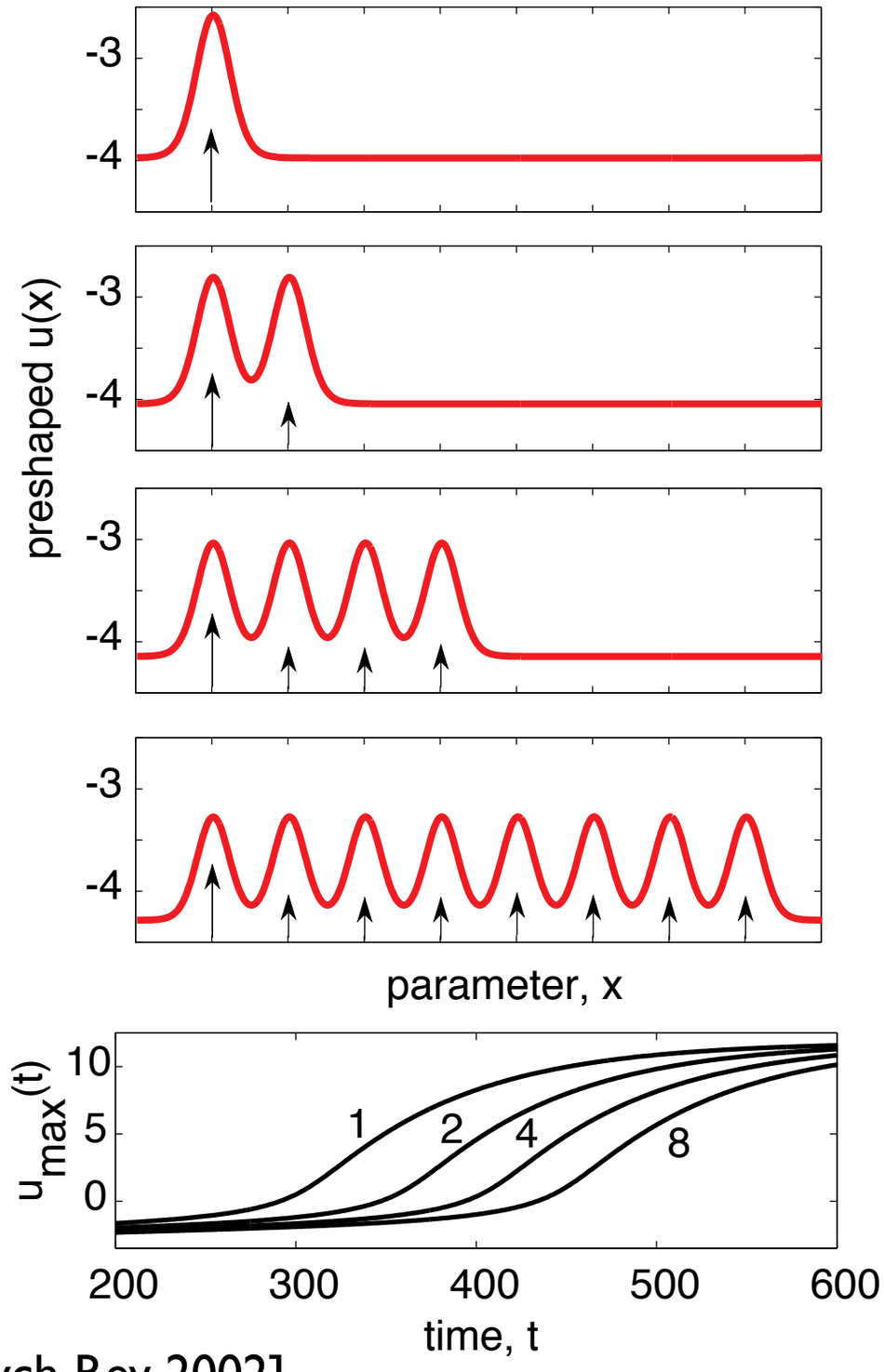


[Wilimzig, Schöner, 2006]

using preshape to account for classical RT data

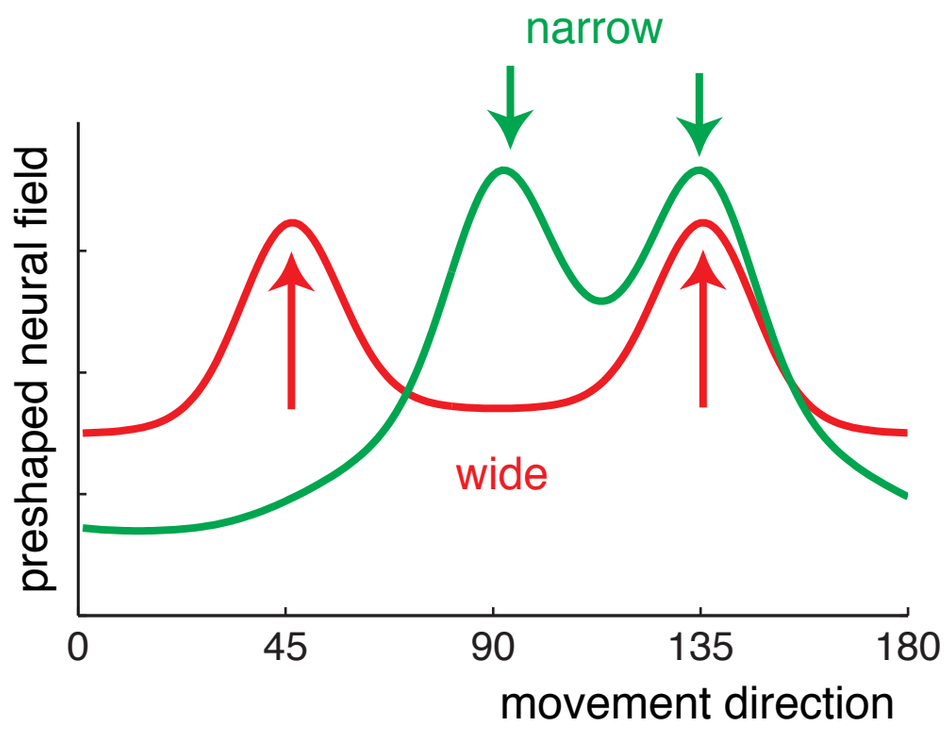
- Hick's law: RT increases with the number of choices



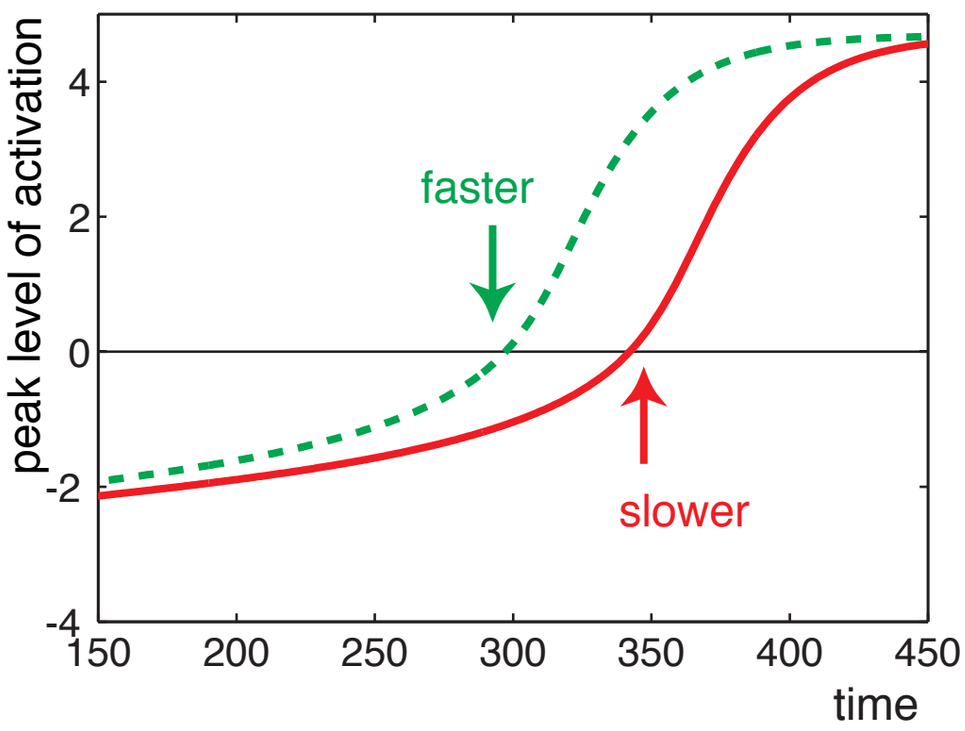


[Erlhagen, Schöner, Psych Rev 2002]

metric effect

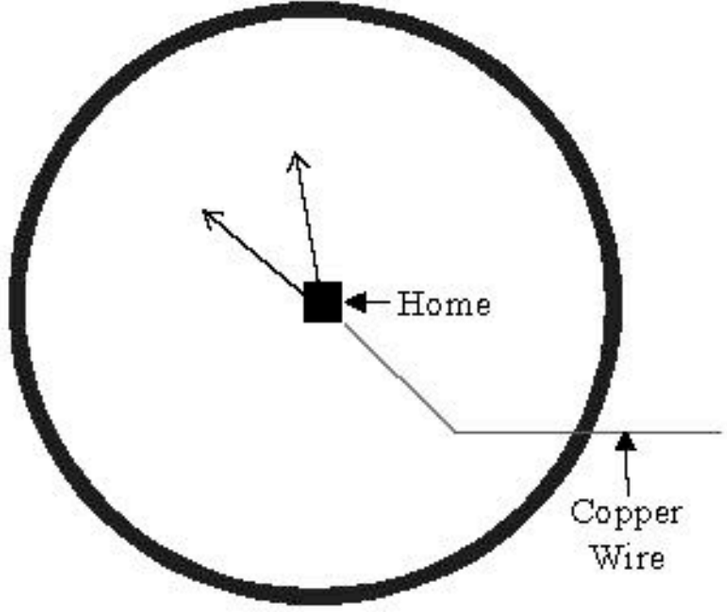


- predict faster response times for metrically close than for metrically far choices

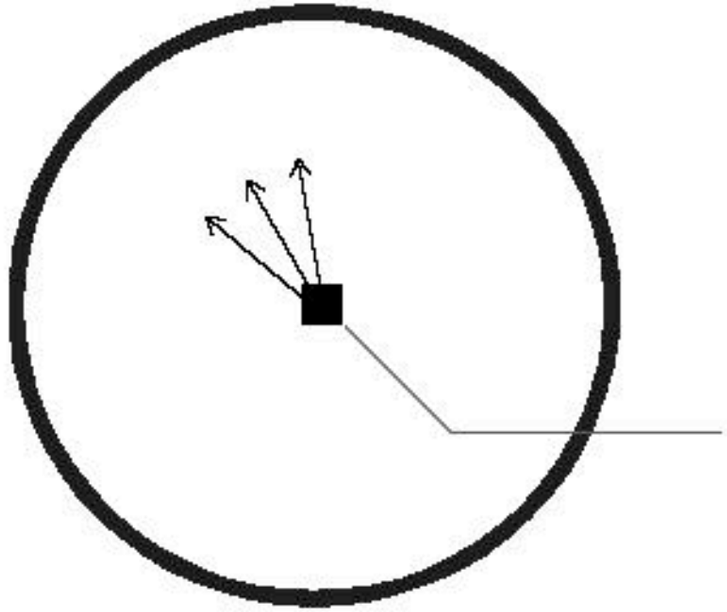


[from Schöner, Kopecz, Erlhagen, 1997]

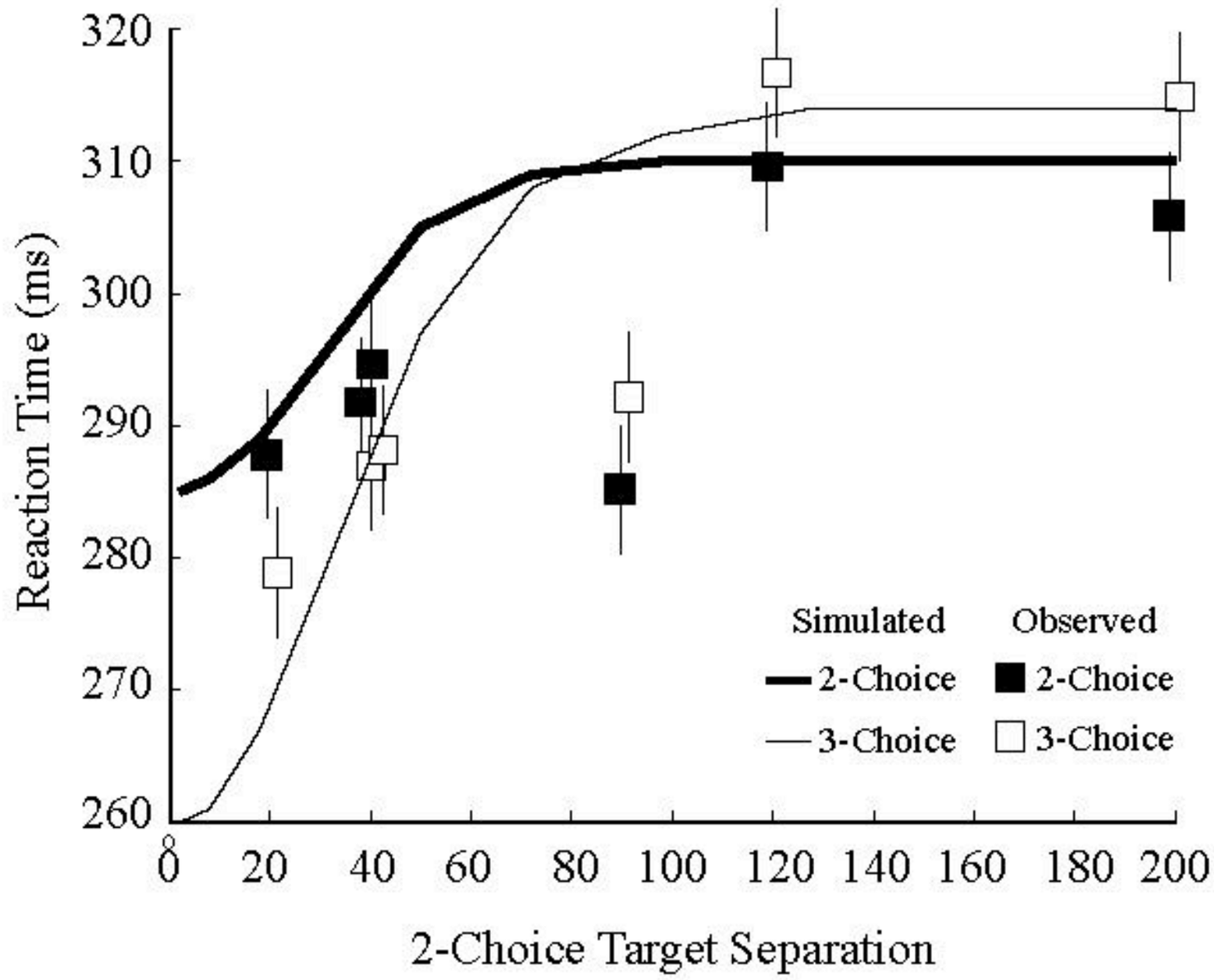
experiment: metric effect



2 - Choice



3 - Choice



[McDowell, Jeka, Schöner]

same metrics, different probability

different metrics, same probability

preshaped activation field

-3

-4

movement parameter

maixmal activation

4

2

0

-2

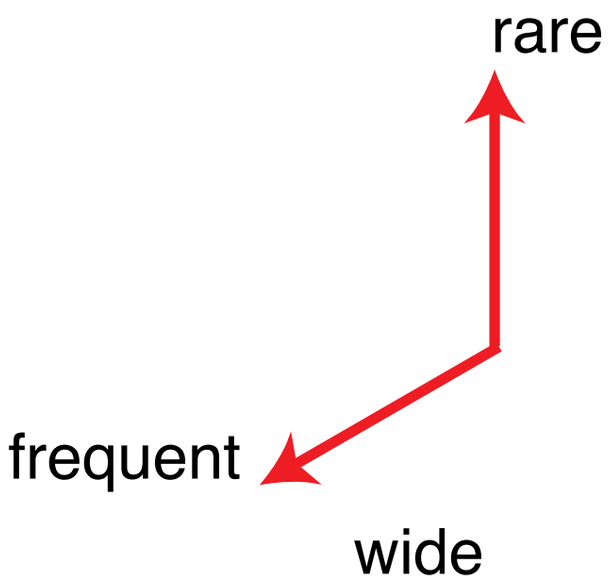
high probability

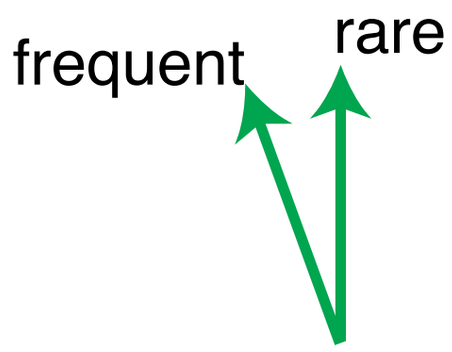
low probability

250 350 450 550

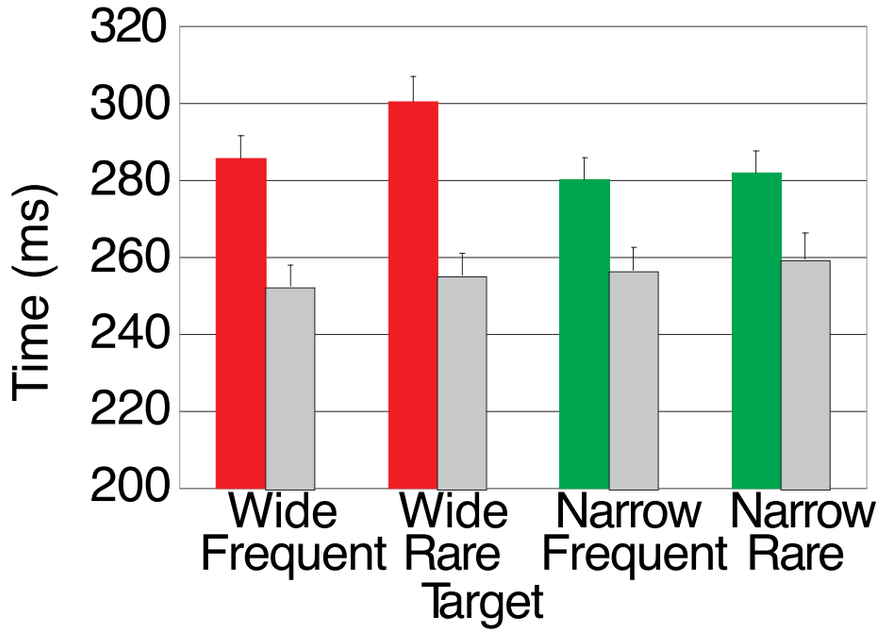
time

[from Erlhagen, Schöner: Psych. Rev. 2002]

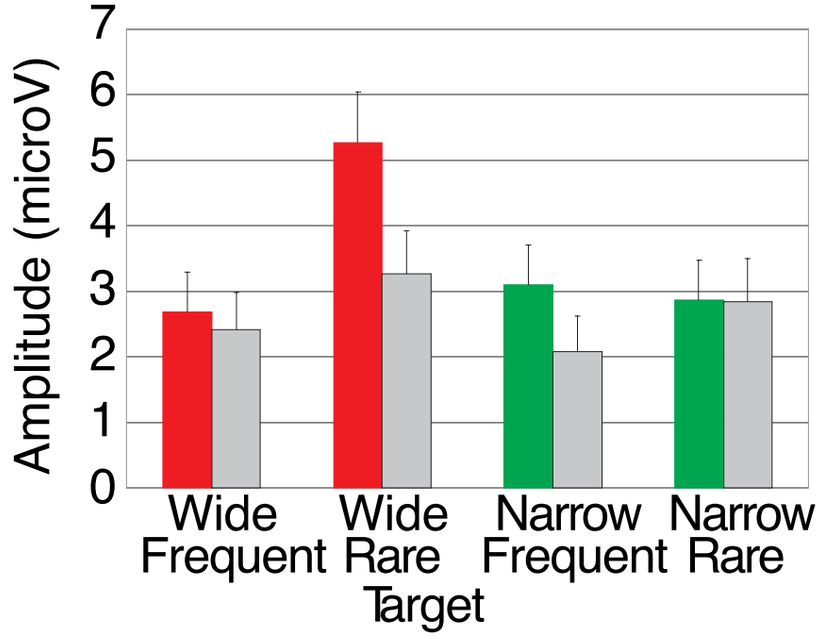




Reaction Time



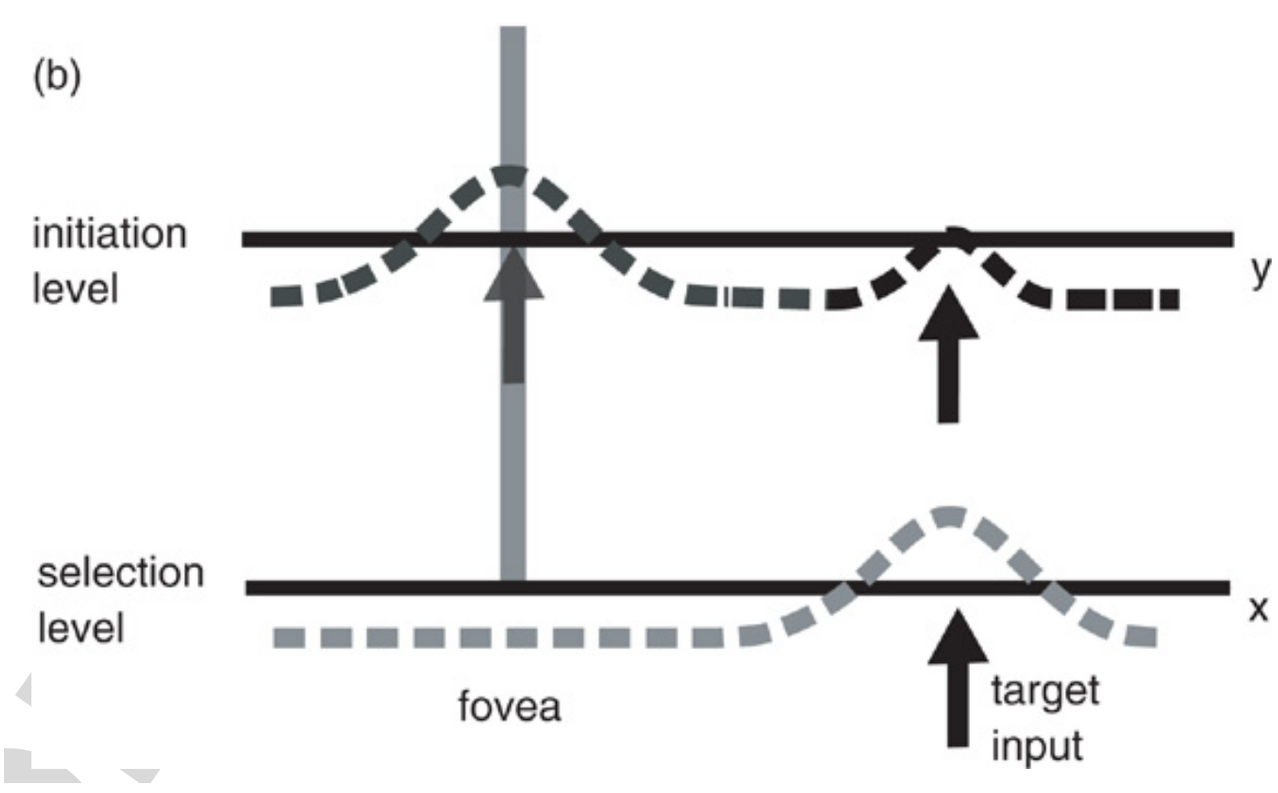
P300 Amplitude Fz

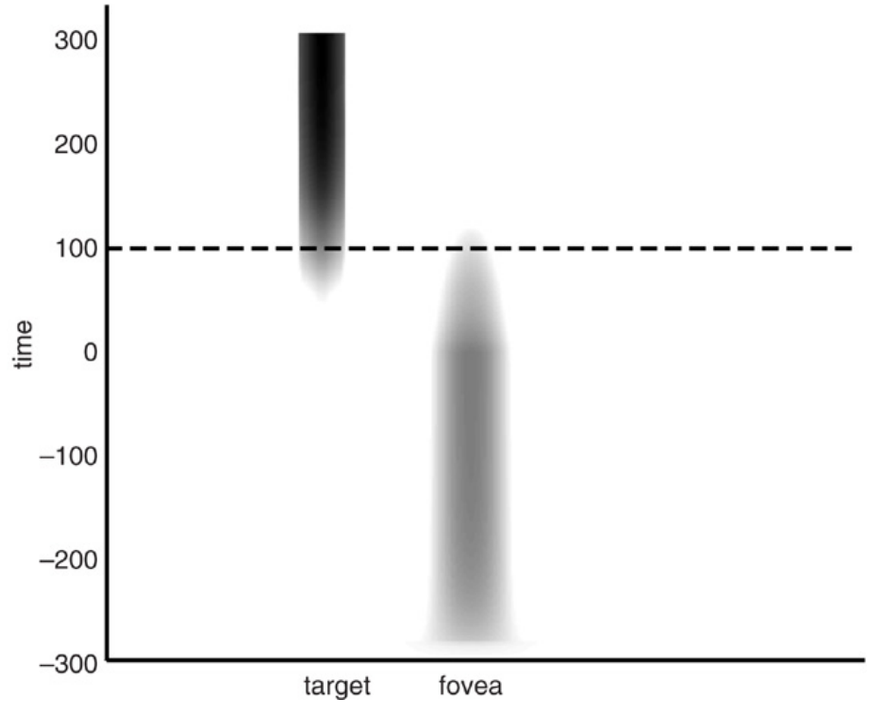


[from McDowell, Jeka, Schöner, Hatfield, 2002]

detection-selection: overcoming fixation

- detection can be like selection: initiating an action means terminating the non-action=fixation or posture
- example: saccade initiation

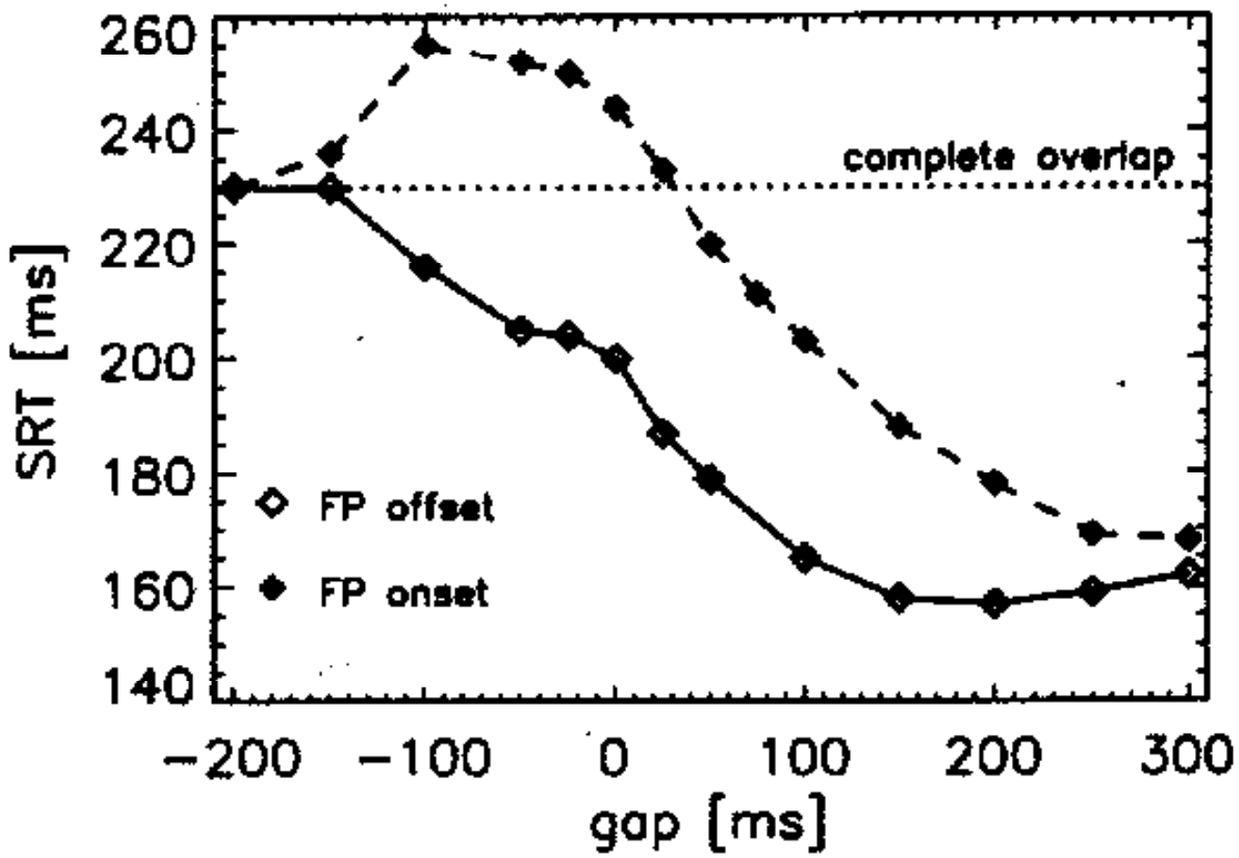


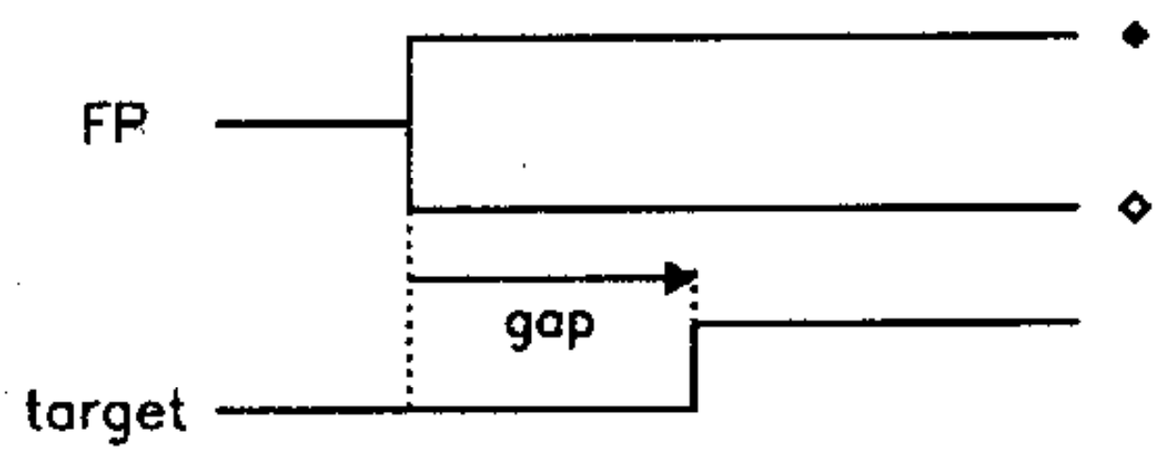


[Wilimzig, Schneider, Schöner, 2006]

initiation vs. fixation

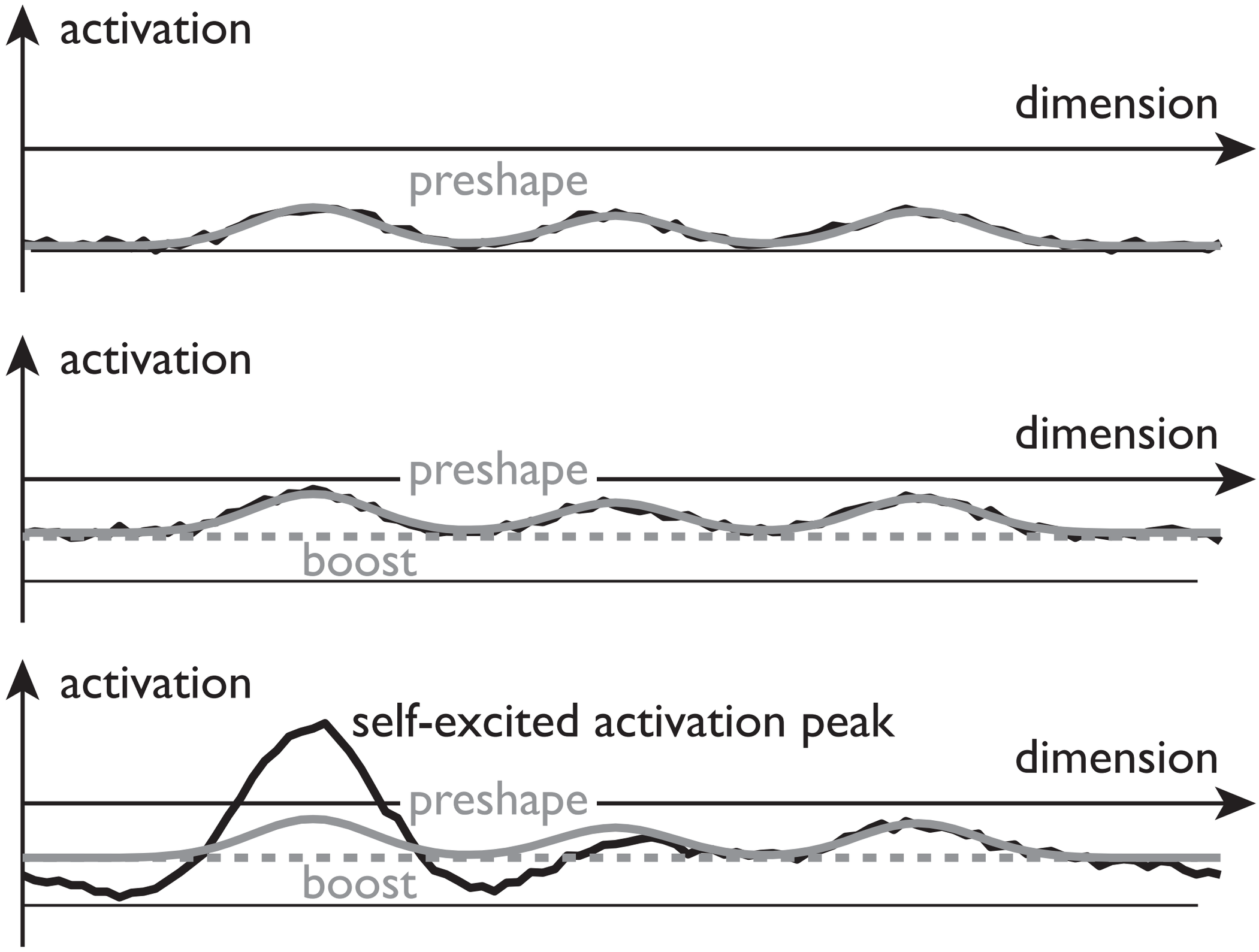
- such models account for the gap-step-overlap effect





[Kopecz, 95]

boost-induced detection instability



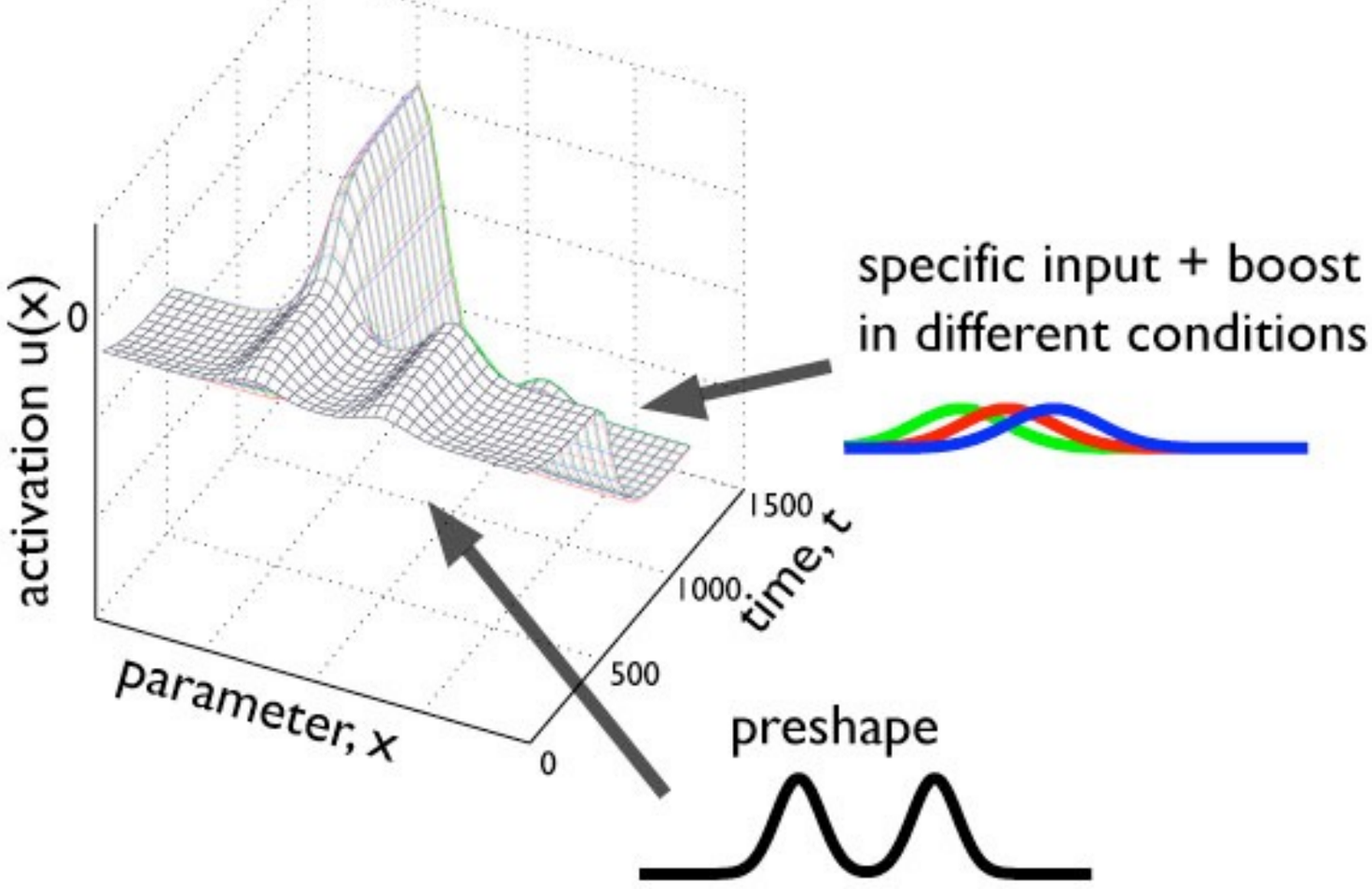
boost-driven detection instability

- inhomogeneities in the field existing prior to a signal/stimulus that leads to a macroscopic response="preshape"
- the boost-driven detection instability amplifies preshape into macroscopic selection decisions

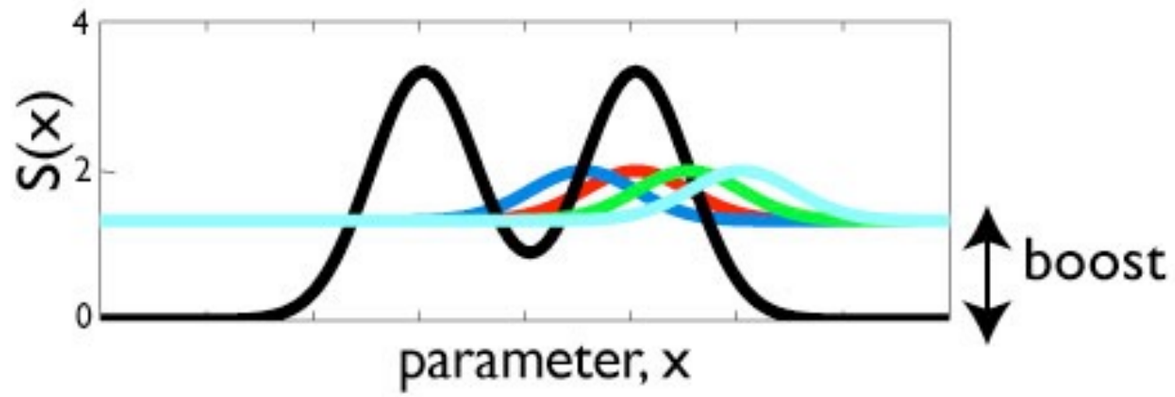
… emergence of categories?

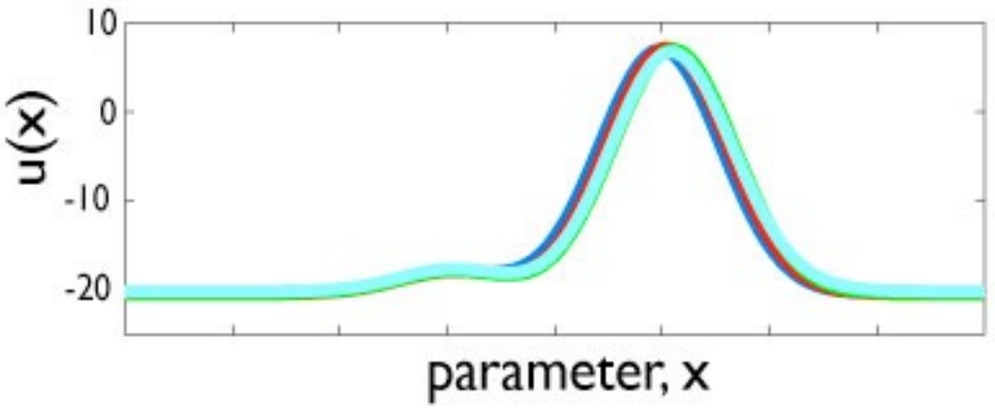
- if we understand, how such inhomogeneities come about, we understand the emergence of categories…

this supports categorical behavior



- when preshape dominates

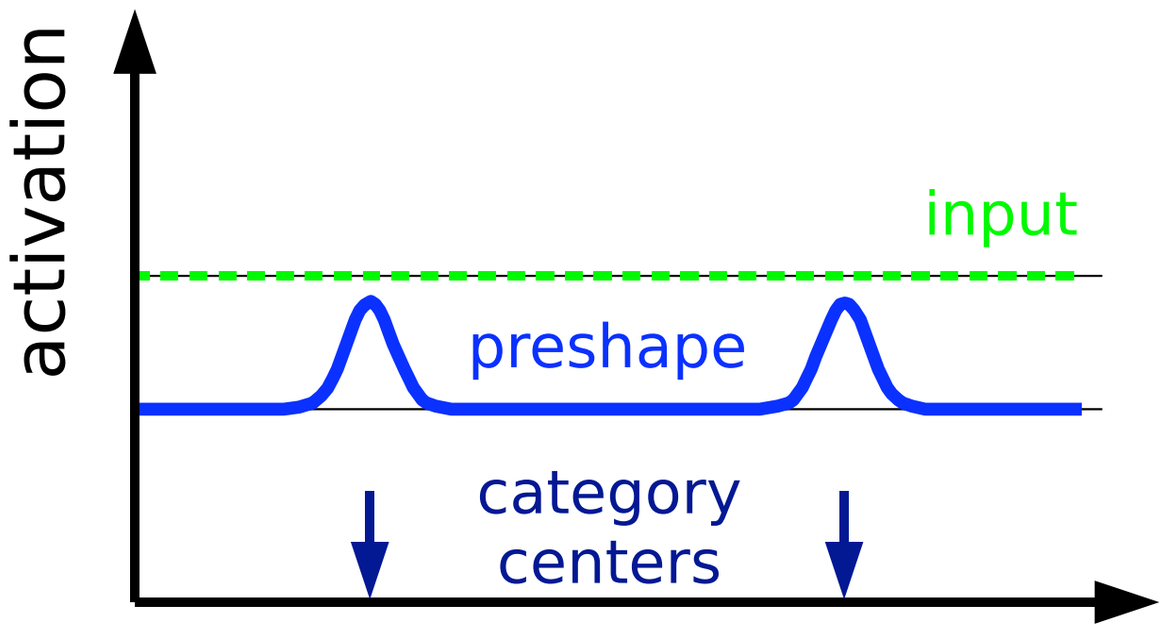


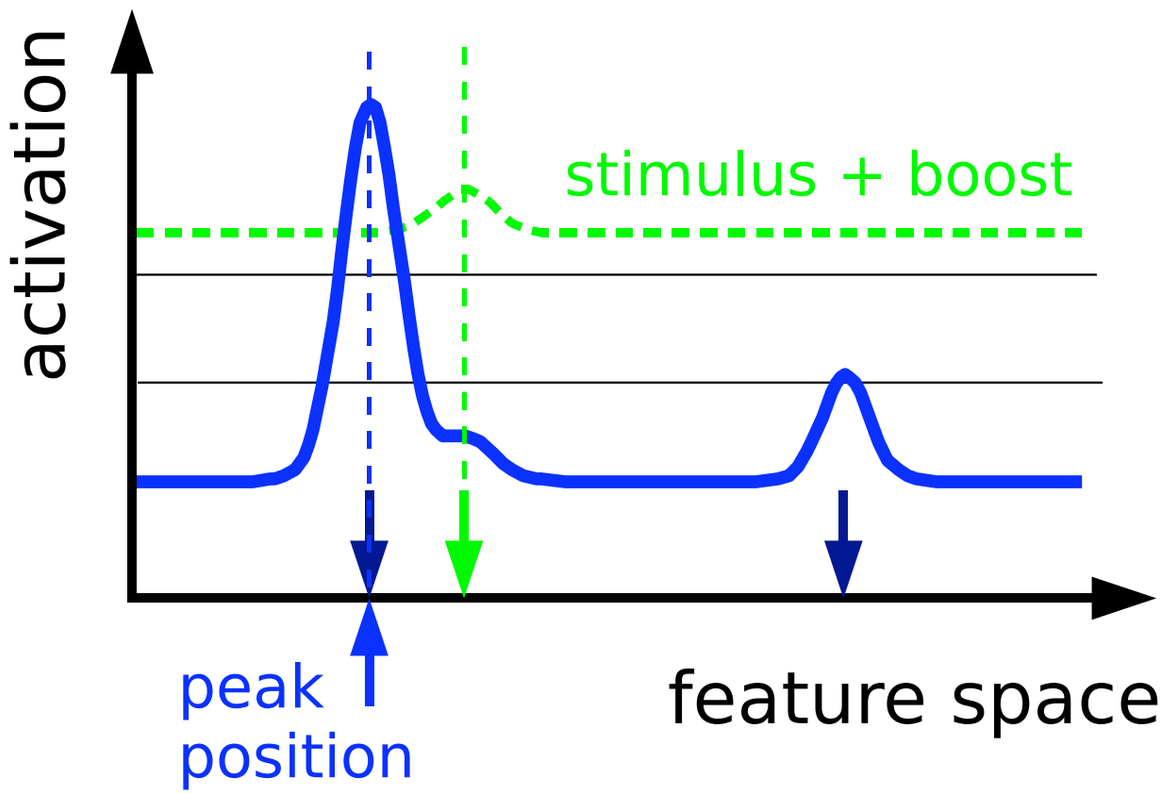


[Wilimzig, Schöner, 2006]

categorical responding

- based on categorical memory trace and boost-driven detection instability



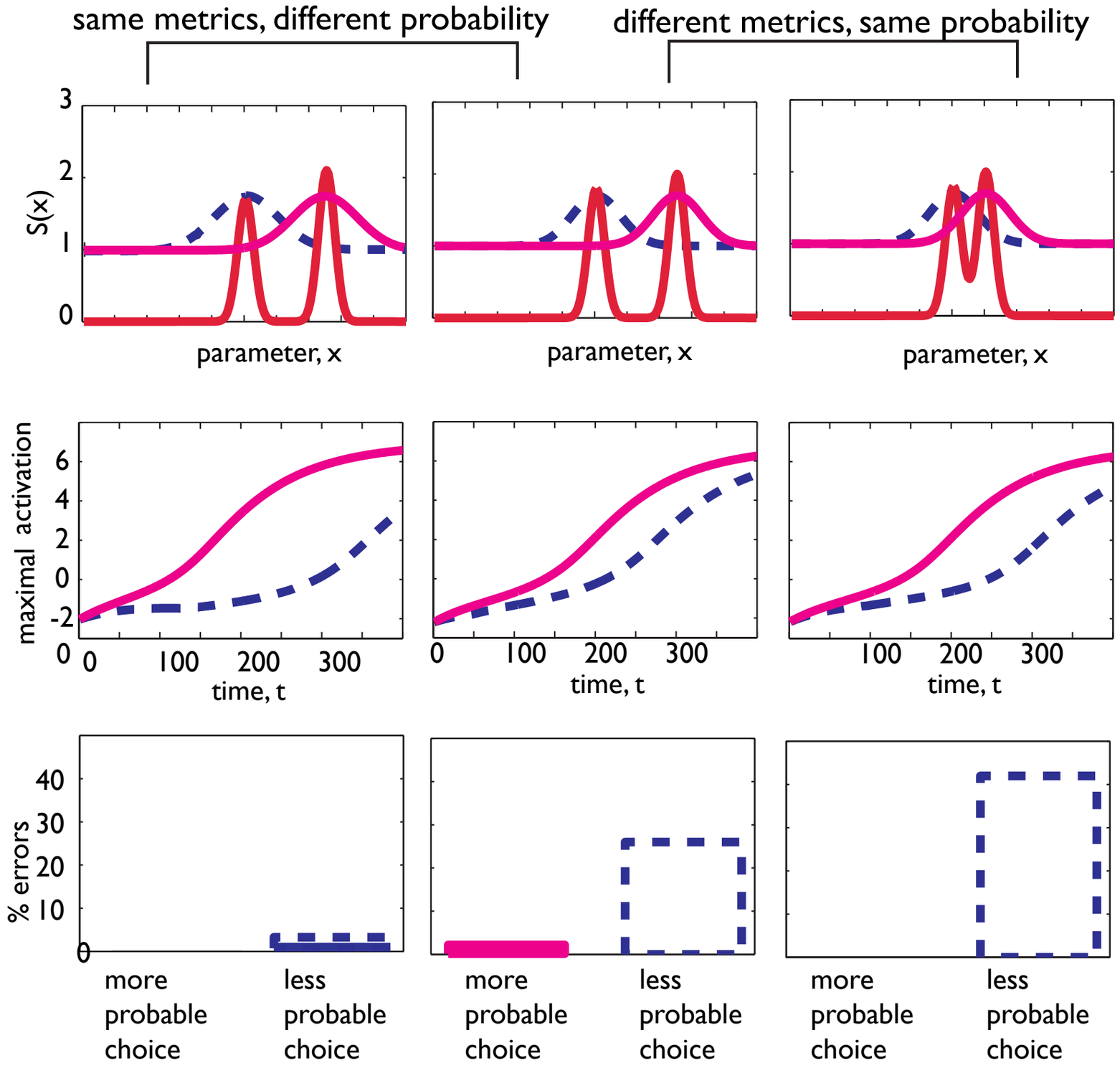


distance effect

- common in categorical tasks… e.g., decide which of two sticks is longer => RT is larger when sticks are more similar in length (1930s')

interaction metrics-probability

- opposite to that predicted for input-driven detection instabilities:
- metrically close choices show larger effect of probability



Wilimzig, Schöner, 2006